

Lecture 3

Complex hyperbolic applications

Course *Block-structured Adaptive Mesh Refinement in C++*

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Outline

Complex geometry

- Boundary aligned meshes
- Cartesian techniques
- Implicit geometry representation
- Accuracy / verification
- Implementation

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- Coupling to a solid mechanics solver
- Implementation
- Rigid body motion
- Thin elastic and deforming thin structures
- Deformation from water hammer
- Real-world example

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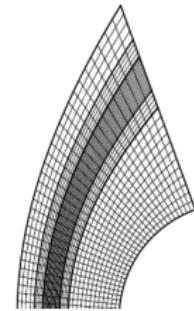
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SAMR on boundary aligned meshes

Analytic or stored geometric mapping of the coordinates
(graphic from [Yamaleev and Carpenter, 2002])

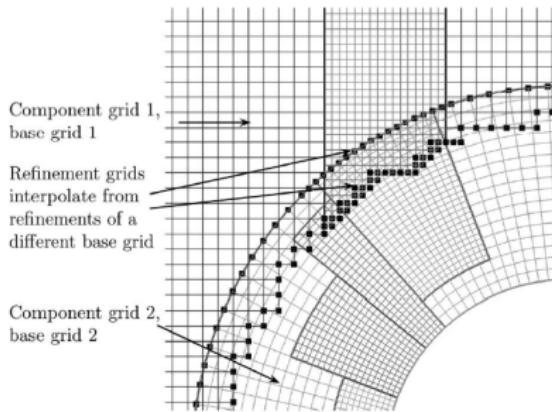
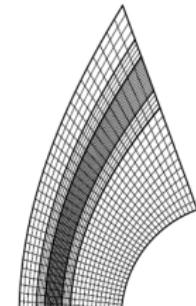
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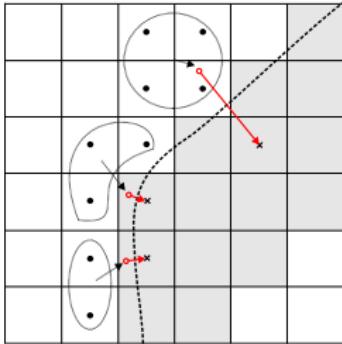
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Overlapping adaptive meshes
 [Henshaw and Schwendeman, 2003],
 [Meakin, 1995]

- ▶ Idea is to use a non-Cartesian structured grids only near boundary
- ▶ Very suitable for moving objects with boundary layers
- ▶ Interpolation between meshes is usually non-conservative

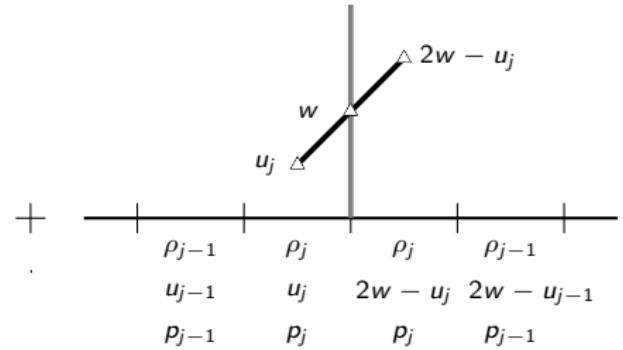
Level-set method for boundary embedding



- Implicit boundary representation via distance function φ , normal $\mathbf{n} = \nabla\varphi/|\nabla\varphi|$
- Complex boundary moving with local velocity \mathbf{w} , treat interface as moving rigid wall
- Construction of values in embedded boundary cells by interpolation / extrapolation

Interpolate / constant value extrapolate values at

$$\tilde{\mathbf{x}} = \mathbf{x} + 2\varphi\mathbf{n}$$



Closest point transform algorithm

The signed distance φ to a surface \mathcal{I} satisfies the eikonal equation [Sethian, 1999]

$$|\nabla \varphi| = 1 \quad \text{with} \quad \varphi|_{\mathcal{I}} = 0$$

Solution smooth but non-differentiable across characteristics.

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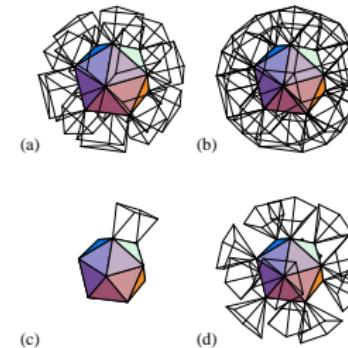
Distance computation trivial for non-overlapping elementary shapes but difficult to do efficiently for triangulated surface meshes:

- ▶ Geometric solution approach with closest-point-transform algorithm
[Mauch, 2003]

The characteristic / scan conversion algorithm

1. Build the characteristic polyhedrons for the surface mesh

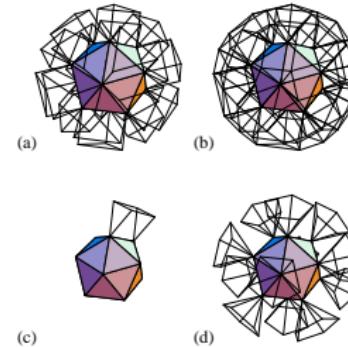
Characteristic polyhedra for faces, edges, and vertices



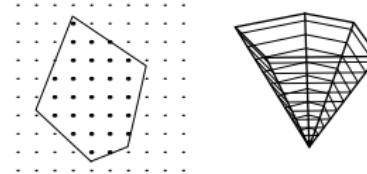
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Slicing and scan conversion of a polygon

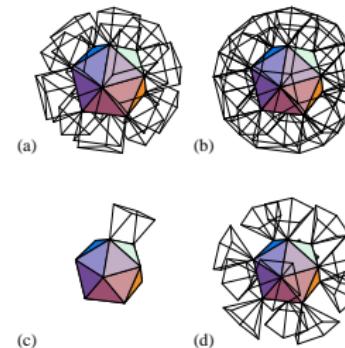


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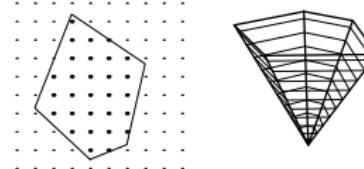
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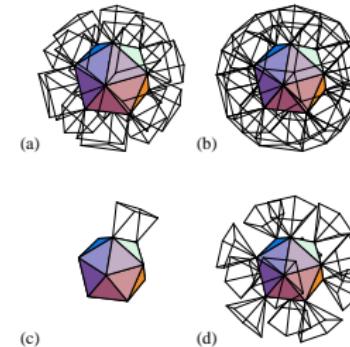
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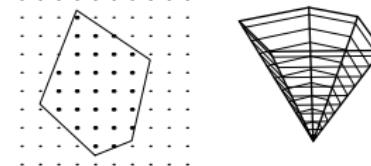
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- 3.** Computational complexity.
 - ▶ $O(m)$ to build the b-rep and the polyhedra.
 - ▶ $O(n)$ to scan convert the polyhedra and compute the distance, etc.

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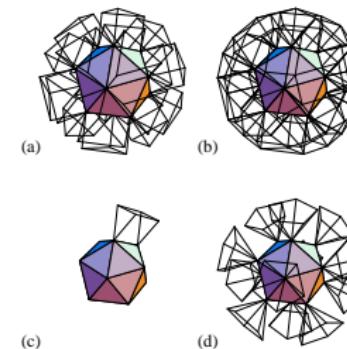
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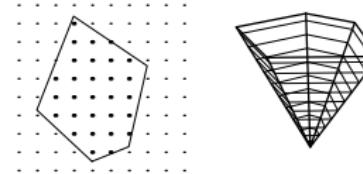
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4. Problem reduction by evaluation only within specified max. distance

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Slicing and scan conversion of a polygon



[Mauch, 2003], see also
[Deiterding et al., 2006]

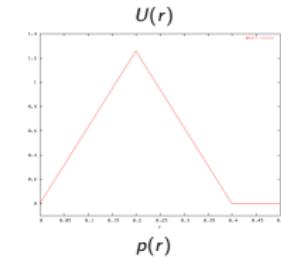
Accuracy test: stationary vortex

Construct non-trivial *radially symmetric* and *stationary* solution by balancing hydrodynamic pressure and centripetal force per volume element, i.e.

$$\frac{d}{dr} p(r) = \rho(r) \frac{U(r)^2}{r}$$

For $\rho_0 \equiv 1$ and the velocity field

$$U(r) = \alpha \cdot \begin{cases} 2r/R & \text{if } 0 < r < R/2, \\ 2(1 - r/R) & \text{if } R/2 \leq r \leq R, \\ 0 & \text{if } r > R, \end{cases}$$



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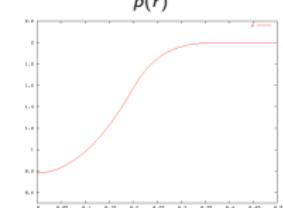
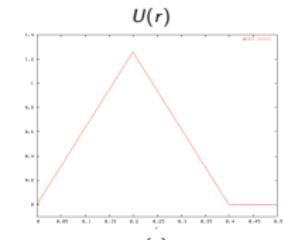
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one gets with boundary condition $p(R) = p_0 \equiv 2$ the pressure distribution

$$p(r) = p_0 + 2\rho_0\alpha^2 \cdot \begin{cases} r^2/R^2 + 1 - 2\log 2 & \text{if } 0 < r < R/2, \\ r^2/R^2 + 3 - 4r/R + 2\log(r/R) & \text{if } R/2 \leq r \leq R, \\ 0 & \text{if } r > R. \end{cases}$$



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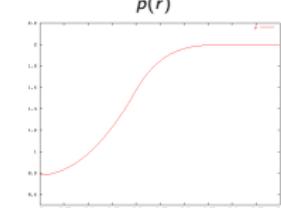
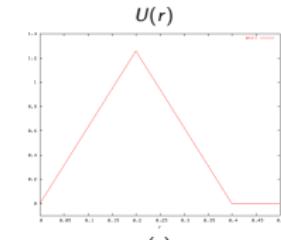
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Entire solution for Euler equations reads

$$\rho(x_1, x_2, t) = \rho_0, \quad u_1(x_1, x_2, t) = -U(r) \sin \phi, \quad u_2(x_1, x_2, t) = U(r) \cos \phi, \quad p(x_1, x_2, t) = p(r)$$

for all $t \geq 0$ with $r = \sqrt{(x_1 - x_{1,c})^2 + (x_2 - x_{2,c})^2}$ and $\phi = \arctan \frac{x_2 - x_{2,c}}{x_1 - x_{1,c}}$



Stationary vortex: results

Compute one full rotation, Roe solver, embedded slip wall boundary conditions
 $x_{1,c} = 0.5, x_{2,c} = 0.5, R = 0.4, t_{end} = 1, \Delta h = \Delta x_1 = \Delta x_2 = 1/N, \alpha = R\pi$

No embedded boundary

N	Wave Propagation		Godunov Splitting	
	Error	Order	Error	Order
20	0.0111235		0.0182218	
40	0.0037996	1.55	0.0090662	1.01
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Marginal shear flow along embedded boundary, $\alpha = R\pi, R_G = R, U_W = 0$

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40	0.0035074	1.78	0.0011898	0.0073070	0.98	0.0001300
80	0.0014193	1.31	0.0001588	0.0038401	0.93	-0.0001036
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Major shear flow along embedded boundary, $\alpha = R\pi, R_G = R/2, U_W = 0$

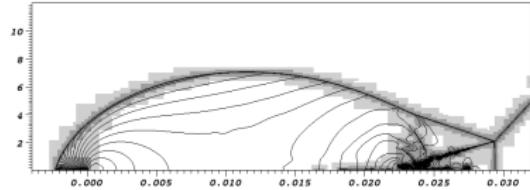
N	Wave Propagation			Godunov Splitting		
	Error	Order	Mass loss	Error	Order	Mass loss
20	0.0423925		0.0423925	0.0271446		0.0271446
40	0.0358735	0.24	0.0358735	0.0242260	0.16	0.0242260
80	0.0212340	0.76	0.0212340	0.0128638	0.91	0.0128638
160	0.0121089	0.81	0.0121089	0.0070906	0.86	0.0070906

Verification: shock reflection

- ▶ Reflection of a Mach 2.38 shock in nitrogen at 43° wedge
- ▶ 2nd order MUSCL scheme with Roe solver, 2nd order multidimensional wave propagation method

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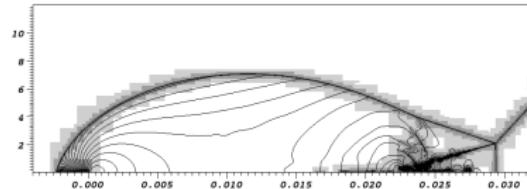
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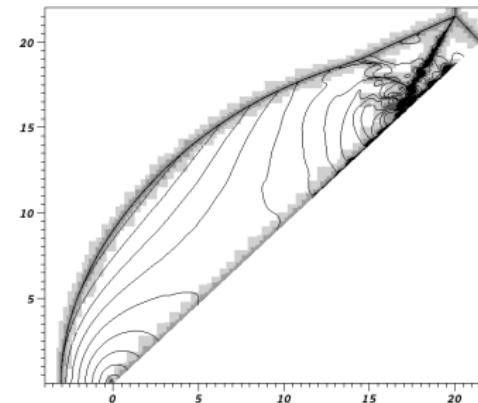
Cartesian base grid 360×160 cells on domain of 36 mm \times 16 mm with up to 3 refinement levels with $r_l = 2, 4, 4$ and $\Delta x_{1,2} = 3.125\mu m$, 38 h CPU

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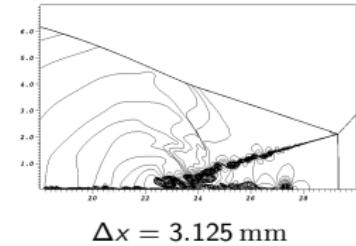
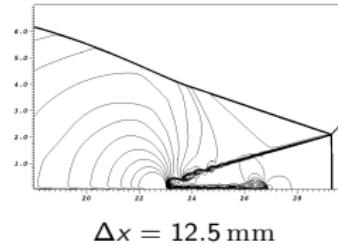
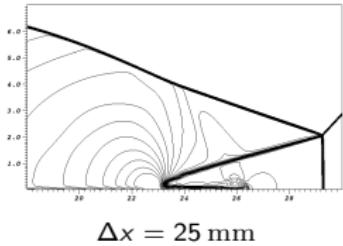


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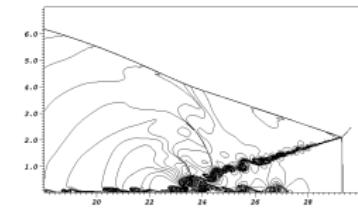
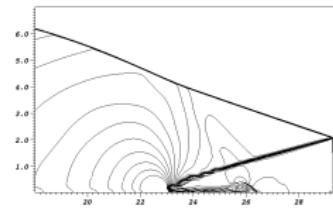
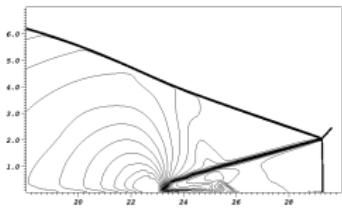
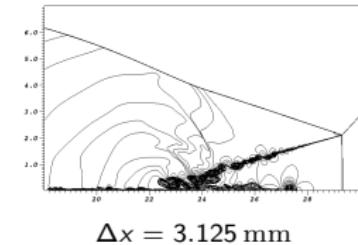
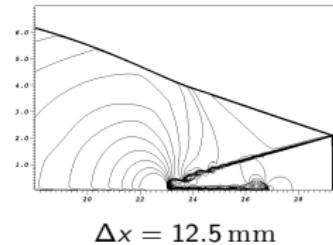
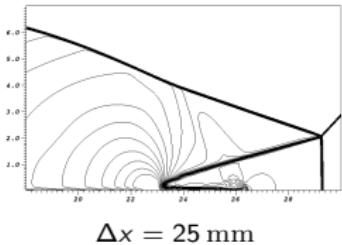


GFM base grid 390×330 cells on domain of $26\text{ mm} \times 22\text{ mm}$ with up to 3 refinement levels with $r_l = 2, 4, 4$ and $\Delta x_{e,1,2} = 2.849\mu\text{m}$, 200 h CPU

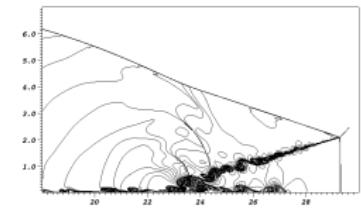
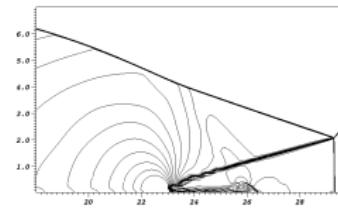
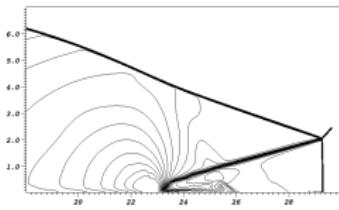
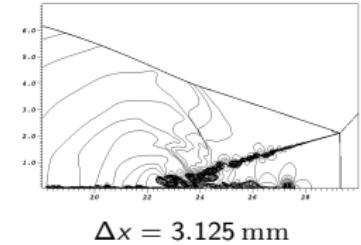
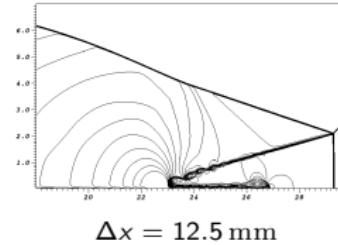
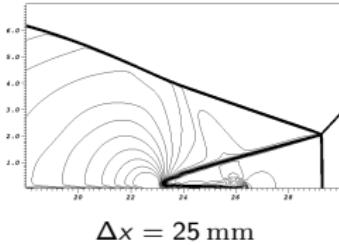
Shock reflection: SAMR solution for Euler equations



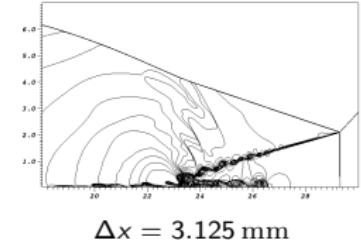
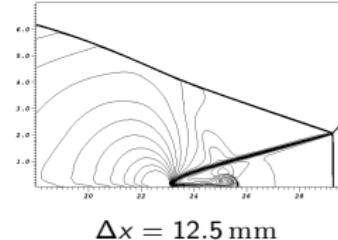
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2nd order MUSCL scheme
with Van Leer FVS, dimen-
sional splitting

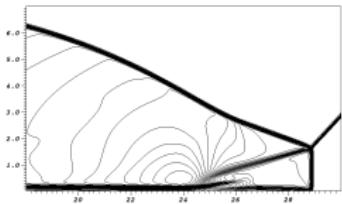
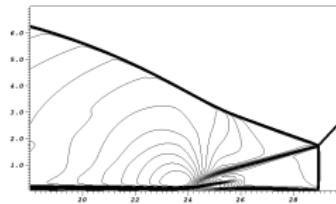
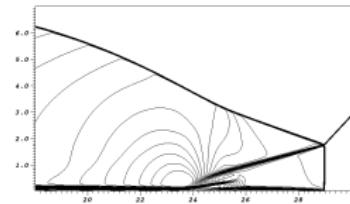


Shock reflection: solution for Navier-Stokes equations

- ▶ No-slip boundary conditions enforced
- ▶ Conservative 2nd order centered differences to approximate stress tensor and heat flow

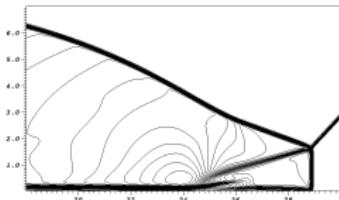
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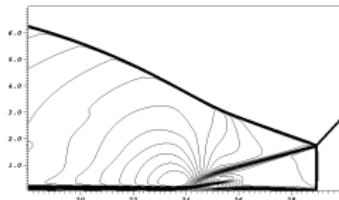
 $\Delta x = 50 \text{ mm}$  $\Delta x = 25 \text{ mm}$  $\Delta x = 12.5 \text{ mm, SAMR}$

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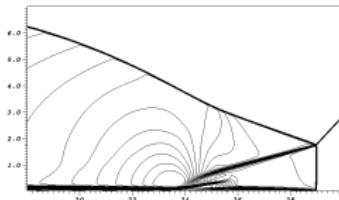
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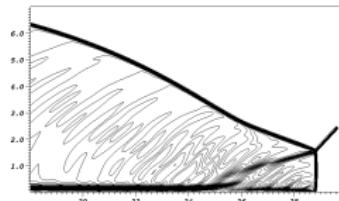
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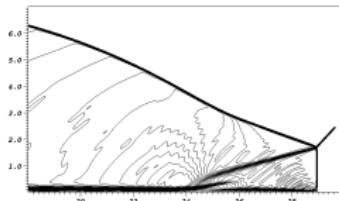
$\Delta x = 25 \text{ mm}$



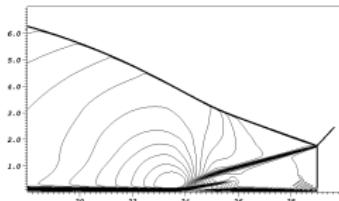
$\Delta x = 12.5 \text{ mm, SAMR}$



$\Delta x_e = 45.6 \text{ mm}$



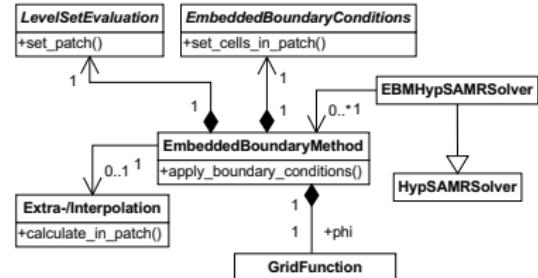
$\Delta x_e = 22.8 \text{ mm}$



$\Delta x_e = 11.4 \text{ mm, SAMR}$

Embedded boundary method

- ▶ Multiple independent EmbeddedBoundaryMethod objects possible
- ▶ Specialization of GFM boundary conditions



Embedded boundary method

- ▶ Multiple independent `EmbeddedBoundaryMethod` objects possible
- ▶ Specialization of GFM boundary conditions
- ▶ The generic embedded boundary method is implemented in `GhostFluidMethod<VectorType, dim >` and has a `GFMLevelSet<DataType, dim >` and `GFBoundary<VectorType, dim >` object.

<code/amroc/doc/html/amr/classGhostFluidMethod.html> <code/amroc/doc/html/amr/classGFMLevelSet.html>

code/amroc/doc/html/amr/classGFBoundary_3_01VectorType_00_012_01_4.html

- ▶ Multiple `GhostFluidMethod<VectorType, dim >` can be registered with `AMRGFMSolver<VectorType, FixupType, FlagType, dim >` and are called as part of the boundary condition setting routine.

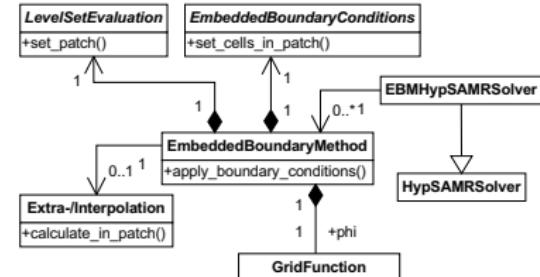
<code/amroc/doc/html/amr/classAMRGFMSolver.html>

- ▶ Interface classes to `GFMLevelSet<DataType, dim >` and `GFBoundary<VectorType, dim >` are available `amroc/amr/F77Interfaces` and in `amroc/amr/Interfaces`

<code/amroc/doc/html/amr/classF77GFBoundary.html> <code/amroc/doc/html/amr/classSchemeGFBoundary.html> make the approach available to all current solvers

- ▶ For instance code/amroc/doc/html/clp/ClpStdGFMProblem_8h.html OR

code/amroc/doc/html/weno/WENOStdGFMProblem_8h.html in `Problem.h` uses `AMRGFMSolver<>`



Outline

Complex geometry

- Boundary aligned meshes
- Cartesian techniques
- Implicit geometry representation
- Accuracy / verification
- Implementation

Combustion

- Equations and FV schemes
- Shock-induced combustion examples

Fluid-structure interaction

- Coupling to a solid mechanics solver
- Implementation
- Rigid body motion
- Thin elastic and deforming thin structures
- Deformation from water hammer
- Real-world example

Governing equations for premixed combustion

Euler equations with reaction terms

$$\frac{\partial \rho_i}{\partial t} + \frac{\partial}{\partial x_n} (\rho_i u_n) = \dot{\omega}_i , \quad i = 1, \dots, K$$

$$\frac{\partial}{\partial t}(\rho u_k) + \frac{\partial}{\partial x_n}(\rho u_k u_n + \delta_{kn} p) = 0, \quad k = 1, \dots, n$$

$$\frac{\partial}{\partial t}(\rho E) + \frac{\partial}{\partial x_n}(u_n(\rho E + p)) = 0$$

Governing equations for premixed combustion

Euler equations with reaction terms

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Ideal gas law and Dalton's law for gas-mixtures

$$p(\rho_1, \dots, \rho_K, T) = \sum_{i=1}^K p_i = \sum_{i=1}^K \rho_i \frac{\mathcal{R}}{W_i} T = \rho \frac{\mathcal{R}}{W} T \quad \text{with} \quad \sum_{i=1}^K \rho_i = \rho, Y_i = \frac{\rho_i}{\rho}$$

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Caloric equation

$$h(Y_1, \dots, Y_K, T) = \sum_{i=1}^K Y_i h_i(T) \quad \text{with} \quad h_i(T) = h_i^0 + \int_0^T c_{pi}(s) ds$$

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Computation of $T = T(\rho_1, \dots, \rho_K, e)$ from implicit equation

$$\sum_{i=1}^K \rho_i h_i(T) - \mathcal{R} T \sum_{i=1}^K \frac{\rho_i}{W_i} - \rho e = 0$$

for *thermally perfect gases* with $\gamma_i(T) = c_{pi}(T)/c_{vi}(T)$

Chemistry

Arrhenius-Kinetics:

$$\dot{\omega}_i = \sum_{j=1}^M (\nu_{ji}^r - \nu_{ji}^f) \left[k_j^f \prod_{n=1}^K \left(\frac{\rho_n}{W_n} \right)^{\nu_{jn}^f} - k_j^r \prod_{n=1}^K \left(\frac{\rho_n}{W_n} \right)^{\nu_{jn}^r} \right] \quad i = 1, \dots, K$$

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- ▶ Parsing of mechanisms with Chemkin-II
- ▶ Evaluation of $\dot{\omega}_i$ with automatically generated optimized Fortran-77 functions in the line of Chemkin-II

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Integration of reaction rates: ODE integration in $S^{(\cdot)}$ for Euler equations with chemical reaction

- ▶ Standard implicit or semi-implicit ODE-solver subcycles within each cell
- ▶ ρ, e, u_k remain unchanged!

$$\partial_t \rho_i = W_i \dot{\omega}_i(\rho_1, \dots, \rho_K, T) \quad i = 1, \dots, K$$

Use Newton or bisection method to compute T iteratively.

Non-equilibrium mechanism for hydrogen-oxygen combustion

			<i>A</i> [cm, mol, s]	<i>β</i>	<i>E_{act}</i> [cal mol ⁻¹]
1.	H + O ₂	→	O + OH	1.86 × 10 ¹⁴	0.00
2.	O + OH	→	H + O ₂	1.48 × 10 ¹³	0.00
3.	H ₂ + O	→	H + OH	1.82 × 10 ¹⁰	1.00
4.	H + OH	→	H ₂ + O	8.32 × 10 ⁰⁹	1.00
5.	H ₂ O + O	→	OH + OH	3.39 × 10 ¹³	0.00
6.	OH + OH	→	H ₂ O + O	3.16 × 10 ¹²	0.00
7.	H ₂ O + H	→	H ₂ + OH	9.55 × 10 ¹³	0.00
8.	H ₂ + OH	→	H ₂ O + H	2.19 × 10 ¹³	0.00
9.	H ₂ O ₂ + OH	→	H ₂ O + HO ₂	1.00 × 10 ¹³	0.00
10.	H ₂ O + HO ₂	→	H ₂ O ₂ + OH	2.82 × 10 ¹³	0.00
...
30.	OH + M	→	O + H + M	7.94 × 10 ¹⁹	-1.00
31.	O ₂ + M	→	O + O + M	5.13 × 10 ¹⁵	0.00
32.	O + O + M	→	O ₂ + M	4.68 × 10 ¹⁵	-0.28
33.	H ₂ + M	→	H + H + M	2.19 × 10 ¹⁴	0.00
34.	H + H + M	→	H ₂ + M	3.02 × 10 ¹⁵	0.00

Third body efficiencies: $f(O_2) = 0.40$, $f(H_2O) = 6.50$

C. K. Westbrook. Chemical kinetics of hydrocarbon oxidation in gaseous detonations. *J. Combustion and Flame*, 46:191–210, 1982.

Riemann solver for combustion

(S1) Calculate standard Roe-averages $\hat{\rho}$, \hat{u}_n , \hat{H} , \hat{Y}_i , \hat{T} .

(S2) Compute $\hat{\gamma} := \hat{c}_p / \hat{c}_v$ with $\hat{c}_{\{p/v\}i} = \frac{1}{T_R - T_L} \int_{T_L}^{T_R} c_{\{p,v\}i}(\tau) d\tau$.

(S3) Calculate $\hat{\phi}_i := (\hat{\gamma} - 1) \left(\frac{\hat{u}^2}{2} - \hat{h}_i \right) + \hat{\gamma} R_i \hat{T}$ with standard Roe-averages \hat{e}_i or \hat{h}_i .

(S4) Calculate $\hat{c} := \left(\sum_{i=1}^K \hat{Y}_i \hat{\phi}_i - (\hat{\gamma} - 1) \hat{u}^2 + (\hat{\gamma} - 1) \hat{H} \right)^{1/2}$.

(S5) Use $\Delta \mathbf{q} = \mathbf{q}_R - \mathbf{q}_L$ and Δp to compute the wave strengths a_m .

(S6) Calculate $\mathcal{W}_1 = a_1 \hat{\mathbf{r}}_1$, $\mathcal{W}_2 = \sum_{\iota=2}^{K+d} a_\iota \hat{\mathbf{r}}_\iota$, $\mathcal{W}_3 = a_{K+d+1} \hat{\mathbf{r}}_{K+d+1}$.

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- (S8) Evaluate $\rho_{L/R}^*$, $u_{1,L/R}^*$, $e_{L/R}^*$, $c_{1,L/R}^*$ from $\mathbf{q}_L^* = \mathbf{q}_L + \mathcal{W}_1$ and $\mathbf{q}_R^* = \mathbf{q}_R - \mathcal{W}_3$.
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$$\mathbf{F}_{Roe}(q_L, q_R) = \frac{1}{2} (\mathbf{f}(q_L) + \mathbf{f}(q_R) - \sum_{\iota=1}^3 |\tilde{s}_\iota| \mathcal{W}_\iota)$$

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- (S11) Positivity correction: Replace \mathbf{F}_i by

$$\mathbf{F}_i^* = \mathbf{F}_\rho \cdot \begin{cases} Y_i^l, & \mathbf{F}_\rho \geq 0, \\ Y_i^r, & \mathbf{F}_\rho < 0. \end{cases}$$
- (S12) Evaluate maximal signal speed by $S = \max(|s_1|, |s_3|)$.

Riemann solver for combustion: carbuncle fix

Entropy corrections

Riemann solver for combustion: carbuncle fix

Entropy corrections [Harten, 1983]

$$\text{1. } |\tilde{s}_\ell| = \begin{cases} |s_\ell| & \text{if } |s_\ell| \geq 2\eta \\ \frac{|s_\ell^2|}{4\eta} + \eta & \text{otherwise} \end{cases}$$
$$\eta = \frac{1}{2} \max_\ell \{|s_\ell(\mathbf{q}_R) - s_\ell(\mathbf{q}_L)|\}$$

Riemann solver for combustion: carbuncle fix

Entropy corrections [Harten, 1983]
[Harten and Hyman, 1983]

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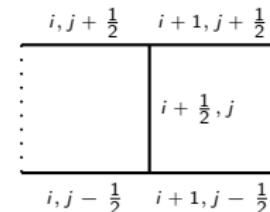
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2D modification of entropy correction
 [Sanders et al., 1998]:



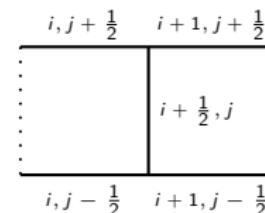
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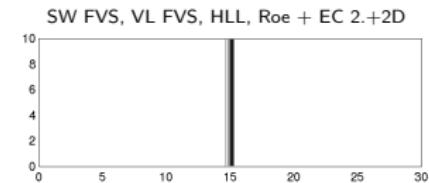
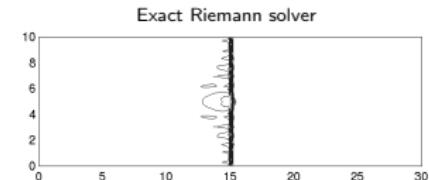
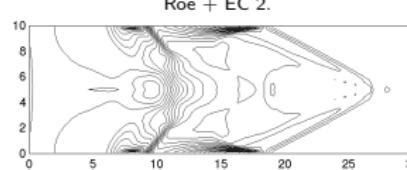
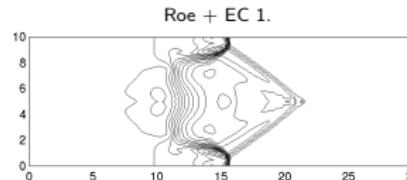
2D modification of entropy correction
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Carbuncle phenomenon

- ▶ [Quirk, 1994b]
- ▶ Test from
 [Deiterding, 2003]

```
code/amroc/doc/html/apps/
clawpack_2applications_2euler_
_znd_22d_2Carbuncle_2src_
2Problem_8h_source.html
```

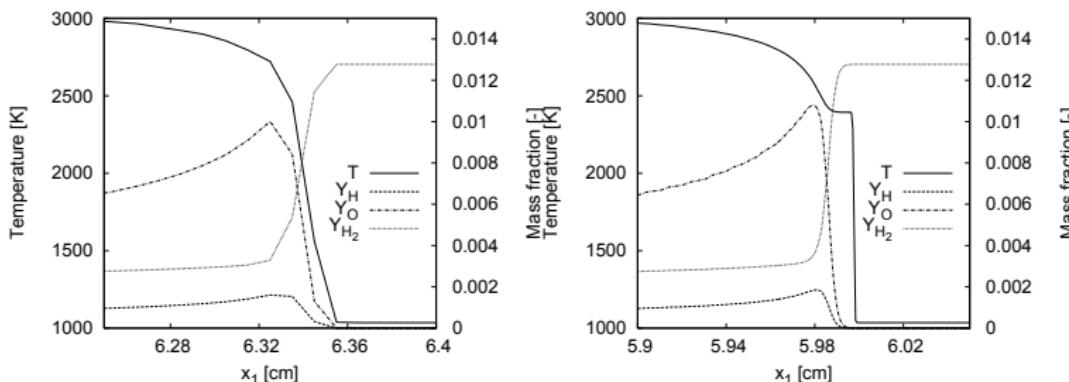


Detonations - motivation for SAMR

- ▶ Extremely high spatial resolution in reaction zone necessary.

Detonations - motivation for SAMR

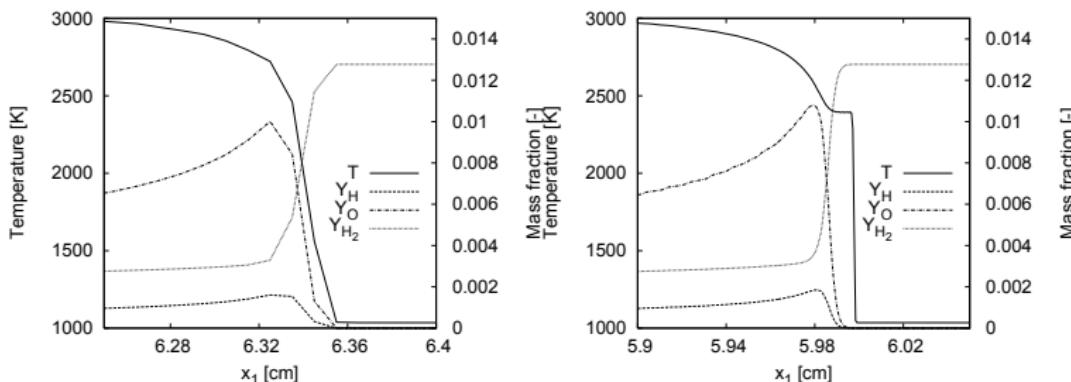
- ▶ Extremely high spatial resolution in reaction zone necessary.
- ▶ Minimal spatial resolution: $7 - 8 \text{ Pts}/l_{ig} \longrightarrow \Delta x_1 \approx 0.2 - 0.175 \text{ mm}$



Approximation of $\text{H}_2 : \text{O}_2$ detonation at $\sim 1.5 \text{ Pts}/l_{ig}$ (left) and $\sim 24 \text{ Pts}/l_{ig}$ (right)

Detonations - motivation for SAMR

- ▶ Extremely high spatial resolution in reaction zone necessary.
- ▶ Minimal spatial resolution: $7 - 8 \text{ Pts}/l_{ig} \rightarrow \Delta x_1 \approx 0.2 - 0.175 \text{ mm}$
- ▶ Uniform grids for typical geometries: $> 10^7 \text{ Pts}$ in 2D, $> 10^9 \text{ Pts}$ in 3D \rightarrow Self-adaptive finite volume method (AMR)



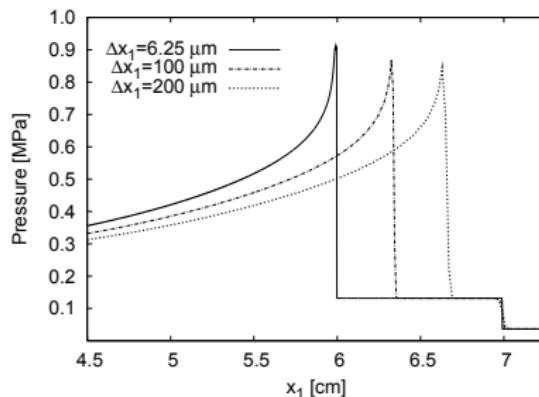
Approximation of $\text{H}_2 : \text{O}_2$ detonation at $\sim 1.5 \text{ Pts}/l_{ig}$ (left) and $\sim 24 \text{ Pts}/l_{ig}$ (right)

Detonation ignition in a shock tube

- ▶ Shock-induced detonation ignition of $H_2 : O_2 : Ar$ mixture at molar ratios 2:1:7 in closed 1d shock tube
- ▶ Insufficient resolution leads to inaccurate results

Detonation ignition in a shock tube

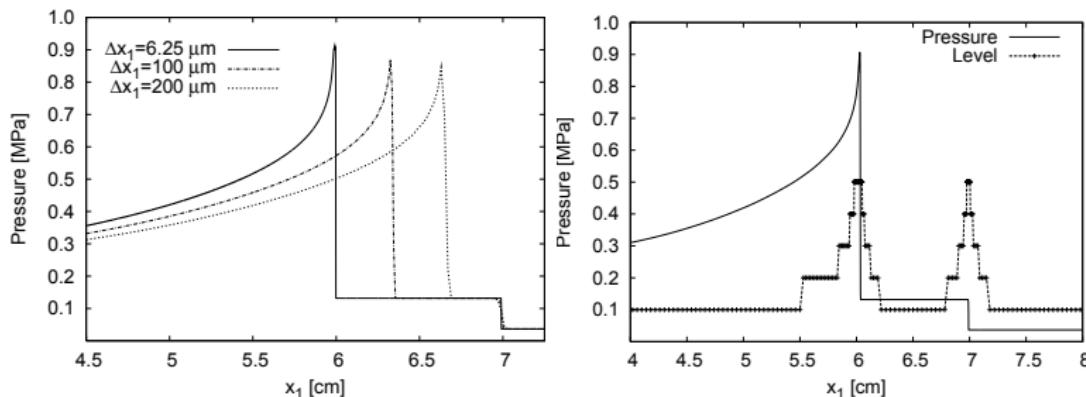
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- ▶ Fine mesh necessary in the induction zone at the head of the detonation

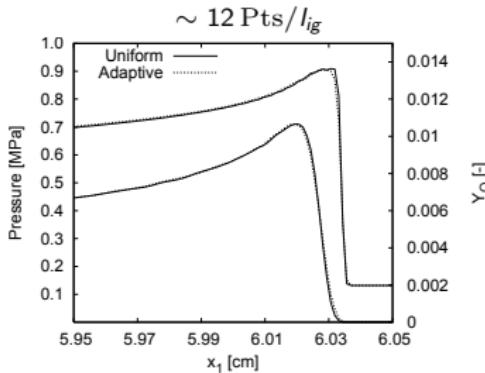


Left: Comparison of pressure distribution $t = 170 \mu\text{s}$ after shock reflection. Right: Domains of refinement levels

Detonation ignition in 1d - adaptive vs. uniform

Uniformly refined vs. dynamic adaptive simulations (Intel Xeon 3.4 GHz CPU)

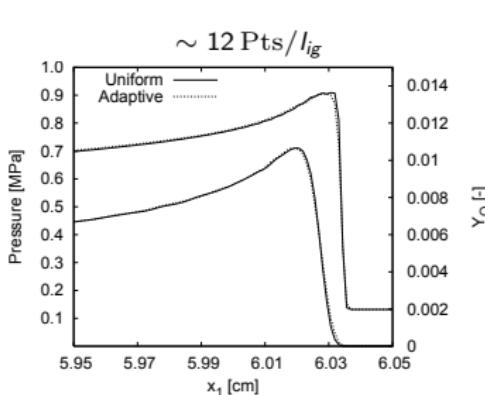
$\Delta x_1 [\mu\text{m}]$	Uniform			Adaptive			
	Cells	$t_m [\mu\text{s}]$	Time [s]	l_{\max}	r_l	$t_m [\mu\text{s}]$	Time [s]
400	300	166.1	31				
200	600	172.6	90	2	2	172.6	99
100	1200	175.5	277	3	2,2	175.8	167
50	2400	176.9	858	4	2,2,2	177.3	287
25	4800	177.8	2713	4	2,2,4	177.9	393
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Refinement criteria:

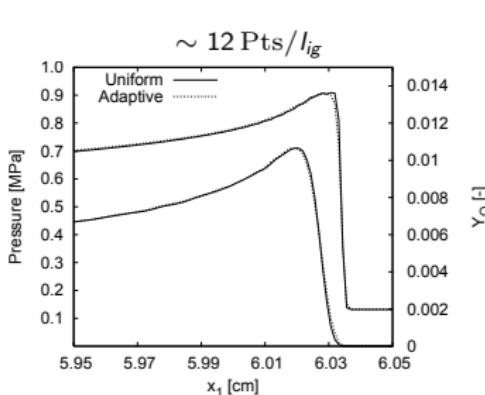
Y_i	$S_{Y_i} \cdot 10^{-4}$	$\eta_{Y_i}^r \cdot 10^{-3}$
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H_2O	7.8	8.0
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$\epsilon_p = 0.07 \text{ kg m}^{-3}, \epsilon_p = 50 \text{ kPa}$

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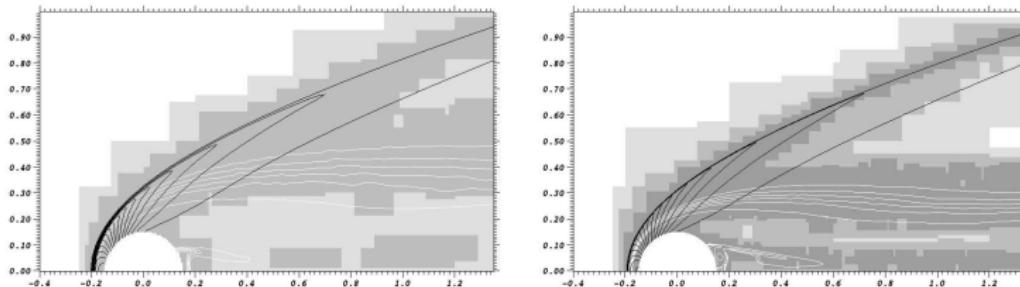
code/amroc/doc/html/apps/clawpack_2applications_2euler__chem_21d_2ReflecDet_2src_2Problem_8h_source.html

Shock-induced combustion around a sphere

- ▶ Spherical projectile of radius 1.5 mm travels with constant velocity $v_I = 2170.6 \text{ m/s}$ through $\text{H}_2 : \text{O}_2 : \text{Ar}$ mixture (molar ratios 2:1:7) at 6.67 kPa and $T = 298 \text{ K}$
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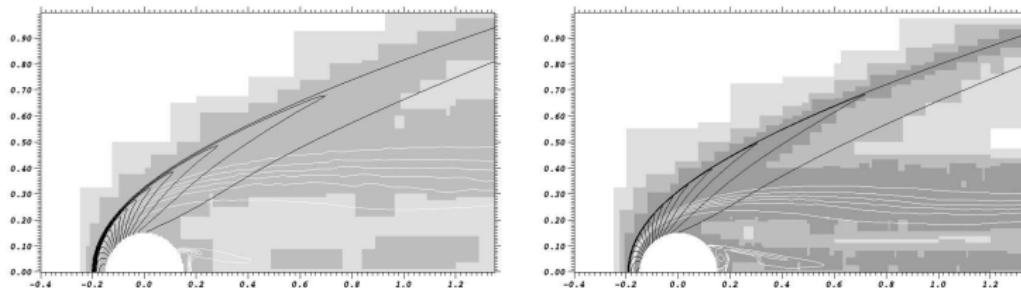


Iso-contours of ρ (black) and Y_{H_2} (white) on refinement domains for 3-level (left) and 4-level computation (right)

code/amroc/doc/html/apps/clawpack_2applications_2euler__chem_22d_2Sphere_2src_2Problem_8h_source.html

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- ▶ Higher resolved computation captures combustion zone visibly better and at slightly different position (see below)

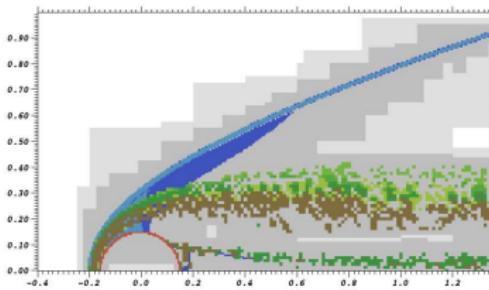


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Combustion around a sphere - adaptation

Refinement indicators on $l = 2$ at $t = 350 \mu\text{s}$.
 Blue: ϵ_p , light blue: ϵ_p , green shades: $\eta_{Y_i}^r$,
 red: embedded boundary



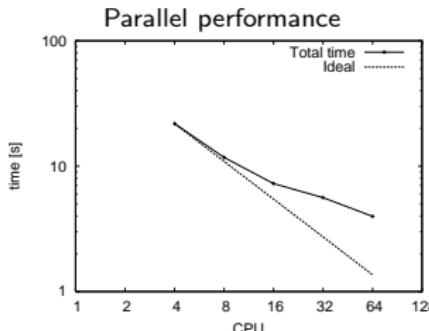
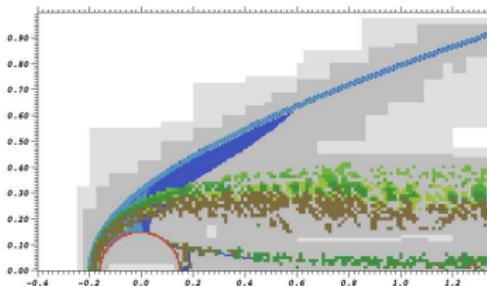
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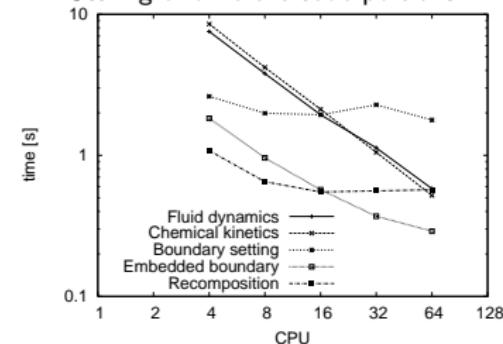


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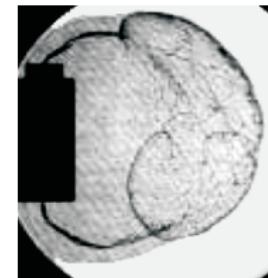
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Scaling of different code portions

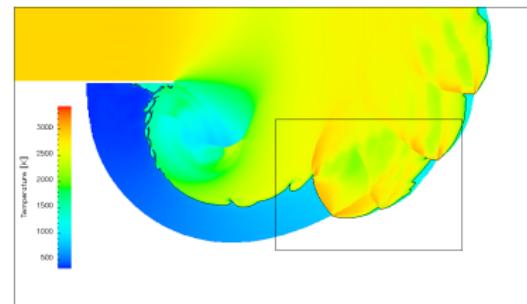


Detonation diffraction

- ▶ CJ detonation for
 $H_2 : O_2 : Ar/2 : 1 : 7$ at
 $T_0 = 298\text{ K}$ and $p_0 = 10\text{ kPa}$.
Cell width $\lambda_c = 1.6\text{ cm}$
- ▶ Adaption criteria (similar as before):
 1. Scaled gradients of ρ and p
 2. Error estimation in Y_i by Richardson extrapolation
- ▶ 25 Pts/ I_{lg} . 5 refinement levels (2,2,2,4).
- ▶ Adaptive computations use up to $\sim 2.2\text{ M}$ instead of $\sim 150\text{ M}$ cells (uniform grid)
- ▶ $\sim 3850\text{ h}$ CPU ($\sim 80\text{ h}$ real time) on 48 nodes Athlon 1.4GHz

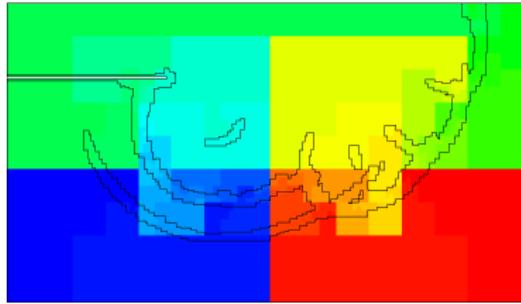


E. Schultz. *Detonation diffraction through an abrupt area expansion*. PhD thesis, California Institute of Technology, Pasadena, California, April 2000.



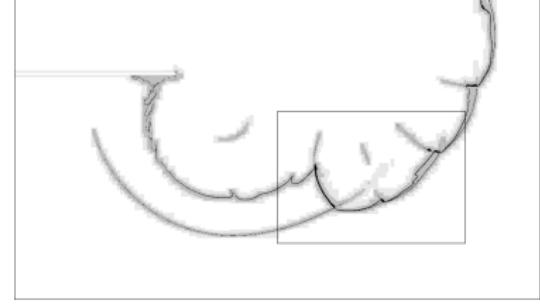
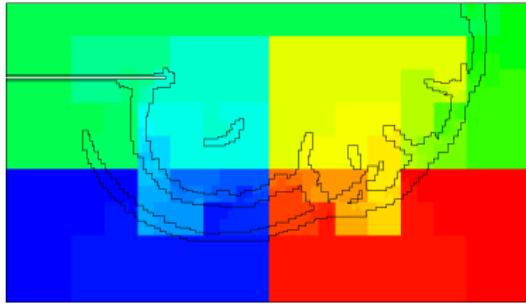
Detonation diffraction - adaptation

Final distribution to 48 nodes and density distribution on four refinement levels



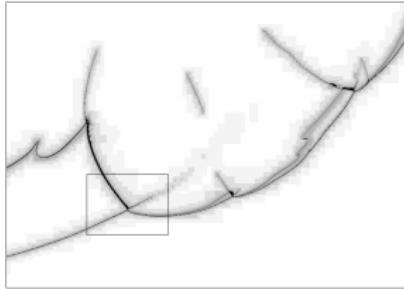
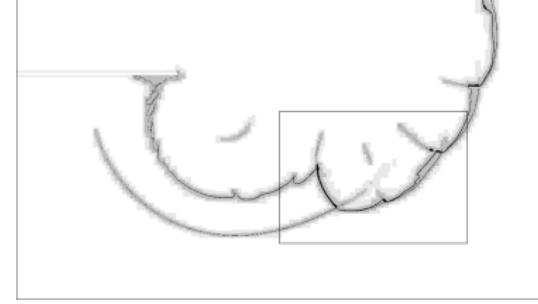
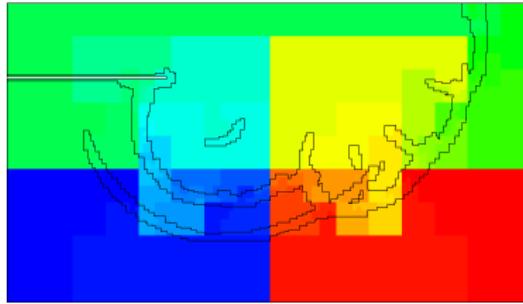
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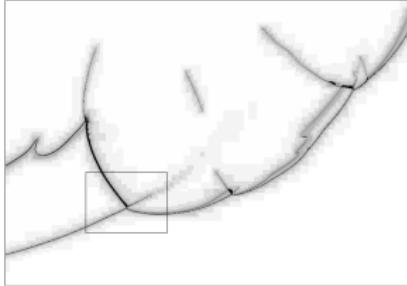
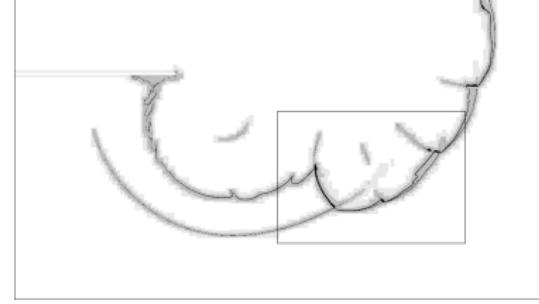
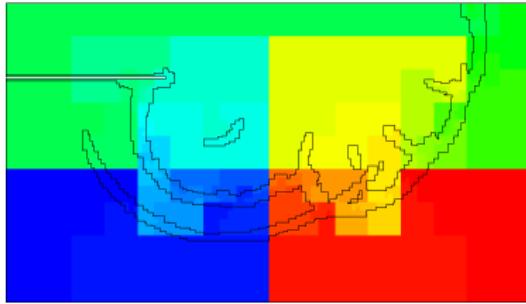
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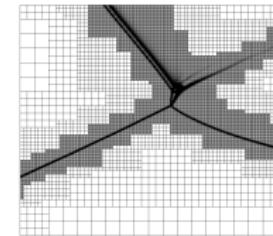
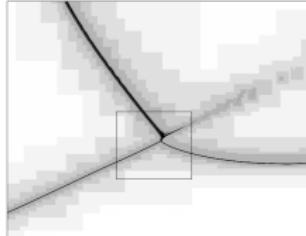
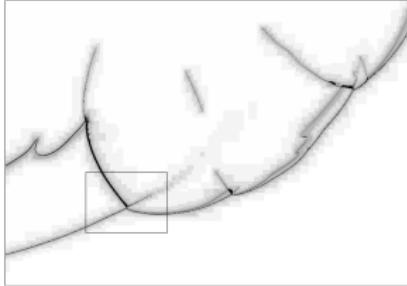
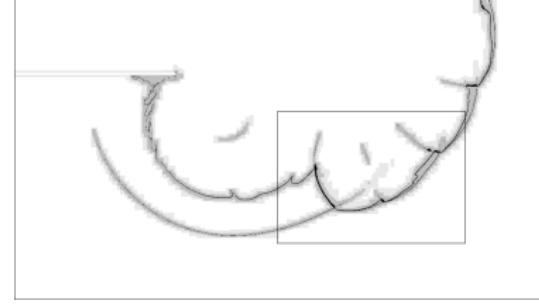
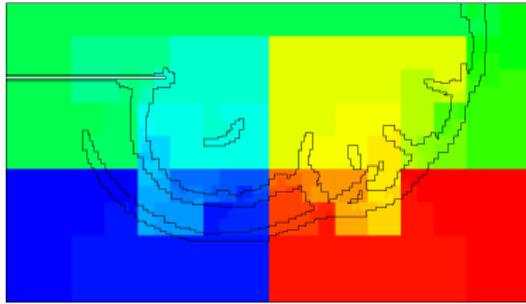
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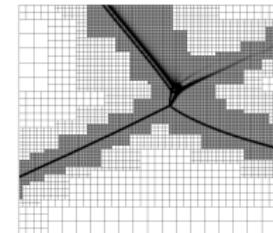
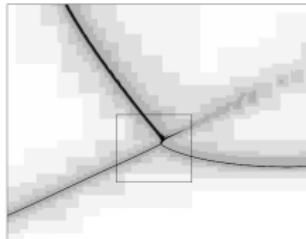
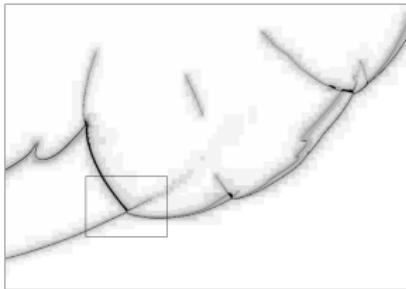
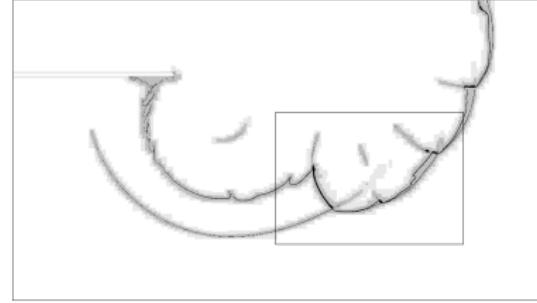
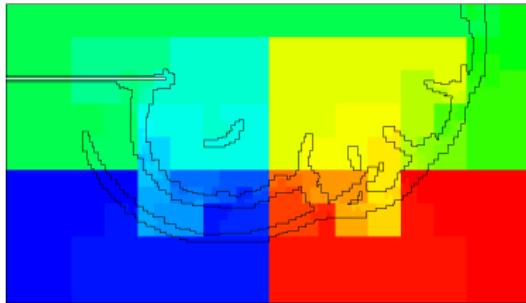
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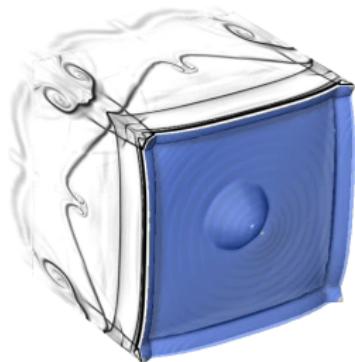


code/amroc/doc/html/apps/clawpack_2applications_2euler__chem_22d_2Diffraction_2src_2Problem_8h_source.html

Detonation cell structure in 3D

- ▶ Simulation of only one quadrant
- ▶ $44.8 \text{ Pts}/l_{ig}$ for $\text{H}_2 : \text{O}_2 : \text{Ar}$ CJ detonation
- ▶ SAMR base grid $400 \times 24 \times 24$, 2 additional refinement levels (2, 4)
- ▶ Simulation uses $\sim 18 \text{ M}$ cells instead of $\sim 118 \text{ M}$ (unigrid)
- ▶ $\sim 51,000 \text{ h}$ CPU on 128 CPU Compaq Alpha.
 $\mathcal{H}: 37.6\%, \mathcal{S}: 25.1\%$

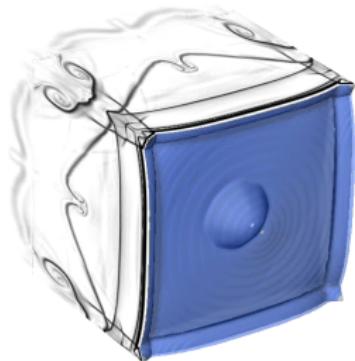
Schlieren and isosurface of Y_{OH}



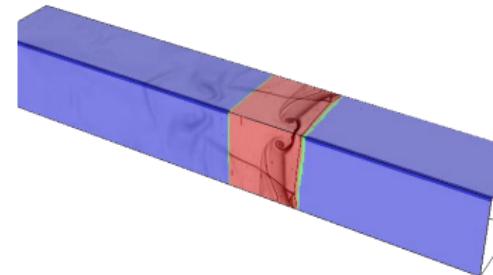
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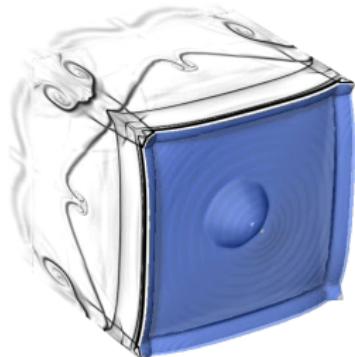
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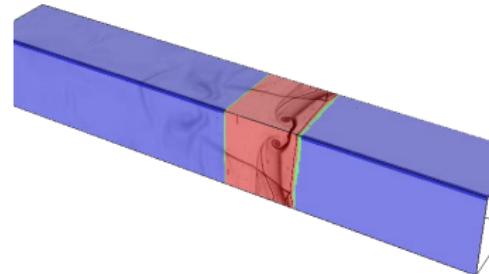
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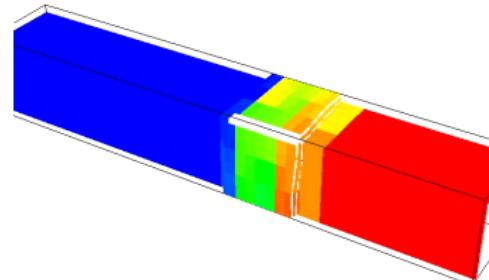
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Schlieren on refinement levels



Distribution to 128 processors



code/amroc/doc/html/apps/clawpack_2applications_2euler__chem_23d_2StrehlowH202_2StatDet_2src_2Problem_8h_source.html

Outline

Complex geometry

- Boundary aligned meshes
- Cartesian techniques
- Implicit geometry representation
- Accuracy / verification
- Implementation

Combustion

- Equations and FV schemes
- Shock-induced combustion examples

Fluid-structure interaction

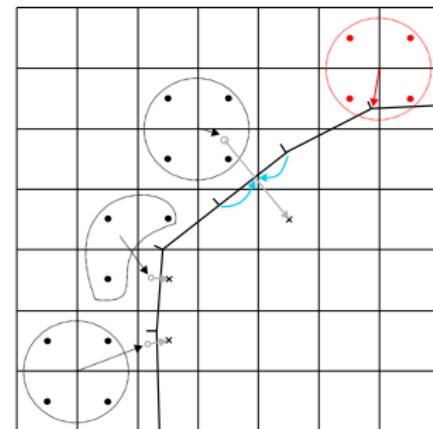
- Coupling to a solid mechanics solver
- Implementation
- Rigid body motion
- Thin elastic and deforming thin structures
- Deformation from water hammer
- Real-world example

Construction of coupling data

- ▶ Moving boundary/interface is treated as a moving contact discontinuity and represented by level set
[Fedkiw, 2002][Arienti et al., 2003]

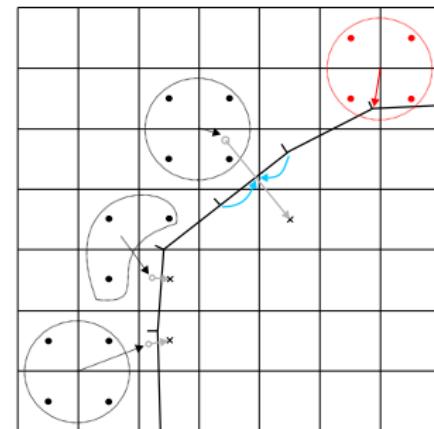
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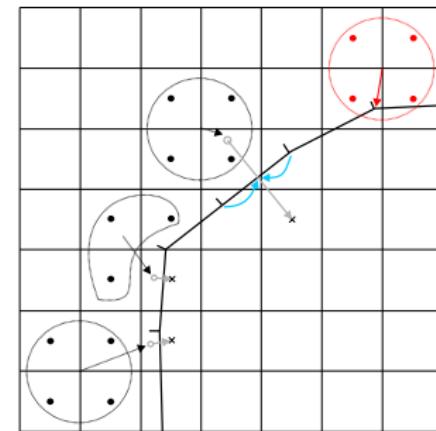
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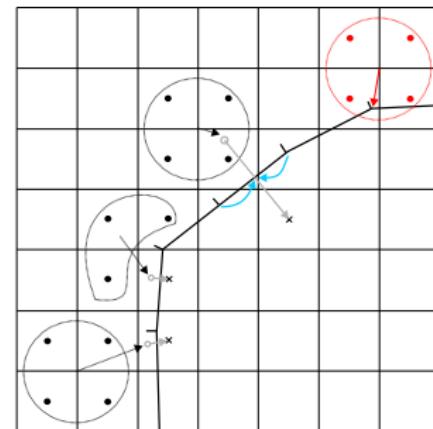
Coupling conditions on interface

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- ▶ Explicit coupling possible if geometry and velocities are prescribed for the more compressible medium
[Specht, 2000]

$$\begin{aligned}
 u_n^F &:= u_n^S(t)|_{\mathcal{I}} \\
 \text{UpdateFluid}(\Delta t) \\
 \sigma_{nn}^S &:= p^F(t + \Delta t)|_{\mathcal{I}} \\
 \text{UpdateSolid}(\Delta t) \\
 t &:= t + \Delta t
 \end{aligned}$$



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- ▶ Nevertheless: Inserting sub-steps accommodates for time step reduction from the solid solver within an SAMR cycle

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 - ▶ Additional levels can be used resolve geometric ambiguities
- ▶ Nevertheless: Inserting sub-steps accommodates for time step reduction from the solid solver within an SAMR cycle
- ▶ Communication strategy:
 - ▶ Updated boundary info from solid solver must be received before regridding operation
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Usage of SAMR

- ▶ Eulerian SAMR + non-adaptive Lagrangian FEM scheme
- ▶ Exploit SAMR time step refinement for effective coupling to solid solver
 - ▶ Lagrangian simulation is called only at level $l_c \leq l_{\max}$
 - ▶ SAMR refines solid boundary at least at level l_c
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- ▶ Nevertheless: Inserting sub-steps accommodates for time step reduction from the solid solver within an SAMR cycle
- ▶ Communication strategy:
 - ▶ Updated boundary info from solid solver must be received before regridding operation
 - ▶ Boundary data is sent to solid when highest level available
- ▶ Inter-solver communication (point-to-point or globally) managed on the fly special coupling module

SAMR algorithm for FSI coupling

AdvanceLevel(l)

Repeat r times

Set ghost cells of $\mathbf{Q}^l(t)$

If time to regrid?

 Regrid()

UpdateLevel(l)

If level $l + 1$ exists?

 Set ghost cells of $\mathbf{Q}^l(t + \Delta t_l)$

 AdvanceLevel($l + 1$)

 Average $\mathbf{Q}^{l+1}(t + \Delta t_l)$ onto $\mathbf{Q}^l(t + \Delta t_l)$

$$t := t + \Delta t_l$$

SAMR algorithm for FSI coupling

AdvanceLevel(l)

Repeat r times

Set ghost cells of $\mathbf{Q}^l(t)$

CPT(φ^l , C^l , \mathcal{I} , δ_l)

If time to regrid?

 Regrid(l)

 UpdateLevel(\mathbf{Q}^l , φ^l , C^l , $\mathbf{u}^S|_{\mathcal{I}}$, Δt_l)

 If level $l+1$ exists?

 Set ghost cells of $\mathbf{Q}^l(t + \Delta t_l)$

 AdvanceLevel($l+1$)

 Average $\mathbf{Q}^{l+1}(t + \Delta t_l)$ onto $\mathbf{Q}^l(t + \Delta t_l)$

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- ▶ Call CPT algorithm before Regrid(l)
- ▶ Include also call to CPT(\cdot) into Recompose(l) to ensure consistent level set data on levels that have changed

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 Average $\mathbf{Q}^{l+1}(t + \Delta t_l)$ onto $\mathbf{Q}^l(t + \Delta t_l)$

If $l = l_c$?

 SendInterfaceData($p^F(t + \Delta t_l)|_{\mathcal{I}}$)

 If $(t + \Delta t_l) < (t_0 + \Delta t_0)$?

 ReceiveInterfaceData(\mathcal{I} , $\mathbf{u}^S|_{\mathcal{I}}$)

$t := t + \Delta t_l$

- ▶ Call CPT algorithm before Regrid(l)
- ▶ Include also call to CPT(\cdot) into Recompose(l) to ensure consistent level set data on levels that have changed
- ▶ Communicate boundary data on coupling level l_c

SAMR algorithm for FSI coupling

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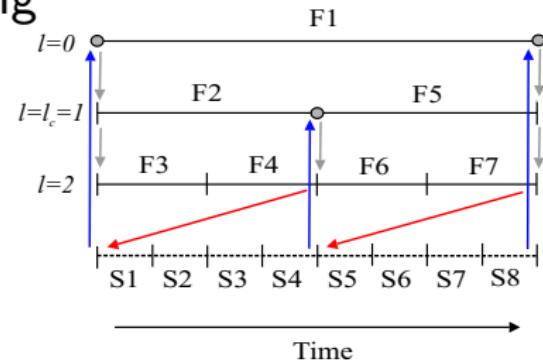
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- ▶ Communicate boundary data on coupling level l_c

Fluid and solid update / exchange of time steps

FluidStep()

$$\Delta\tau_F := \min_{l=0, \dots, l_{\max}} (R_l \cdot \text{StableFluidTimeStep}(l), \Delta\tau_S)$$

$$\Delta t_l := \Delta\tau_F / R_l \text{ for } l = 0, \dots, L$$

ReceiveInterfaceData(\mathcal{I} , $\mathbf{u}^S|_{\mathcal{I}}$)

AdvanceLevel(0)

with $R_l = \prod_{\iota=0}^l r_{\iota}$

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$$\Delta\tau_S := \min(K \cdot R_{l_c} \cdot \text{StableSolidTimeStep}(), \Delta\tau_F)$$

Repeat R_{l_c} times

$$t_{\text{end}} := t + \Delta\tau_S / R_{l_c}, \Delta t := \Delta\tau_S / (K R_{l_c})$$

- ▶ Time step stays constant for R_{l_c} steps, which corresponds to one fluid step at level 0

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While $t < t_{\text{end}}$

SendInterfaceData($\mathcal{I}(t)$, $\vec{u}^S|_{\mathcal{I}}(t)$)

ReceiveInterfaceData($p^F|_{\mathcal{I}}$)

UpdateSolid($p^F|_{\mathcal{I}}$, Δt)

$$t := t + \Delta t$$

$$\Delta t := \min(\text{StableSolidTimeStep}(), t_{\text{end}} - t)$$

with $R_l = \prod_{i=0}^l r_i$

- ▶ Time step stays constant for R_{l_c} steps, which corresponds to one fluid step at level 0

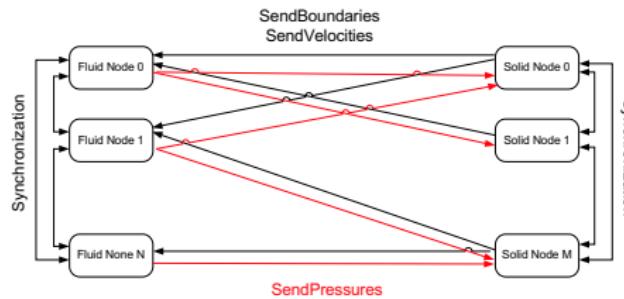
Parallelization strategy for coupled simulations

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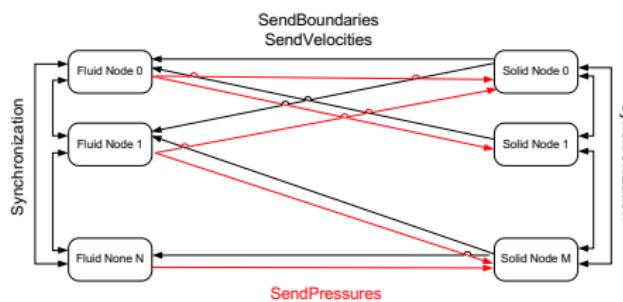
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- ▶ Setting of ghost cell values becomes strictly local operation



Parallelization strategy for coupled simulations

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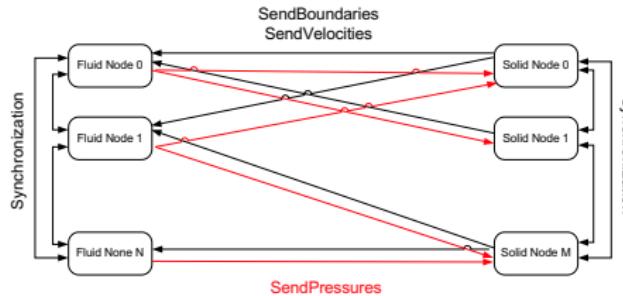
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Parallelization strategy for coupled simulations

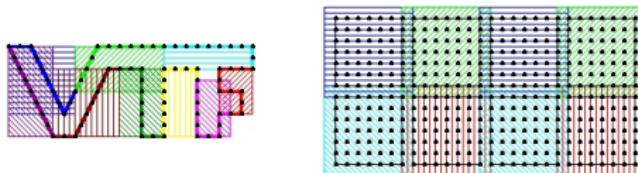
Coupling of an Eulerian FV fluid Solver and a Lagrangian FEM Solver:

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- ▶ Construct new nodal values strictly local on fluid nodes and transfer them back to solid nodes
- ▶ Only surface data is transferred
- ▶ Asynchronous communication ensures scalability
- ▶ Generic encapsulated implementation guarantees reusability



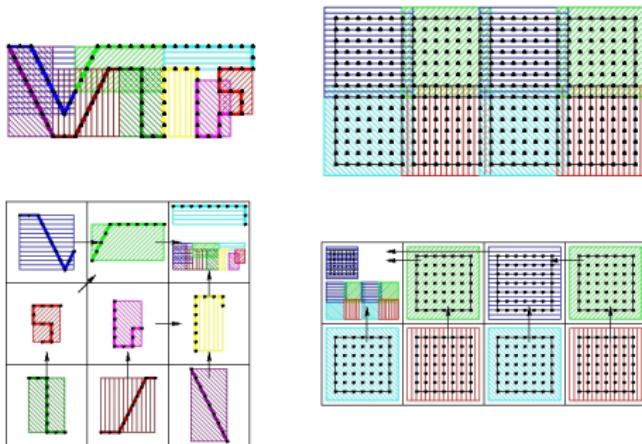
Eulerian/Lagrangian communication module

1. Put bounding boxes around each solid processors piece of the boundary and around each fluid processors grid



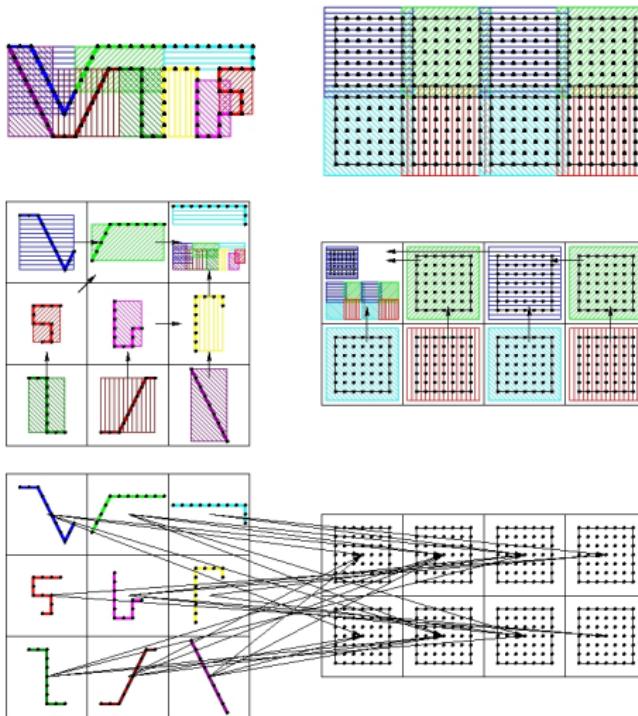
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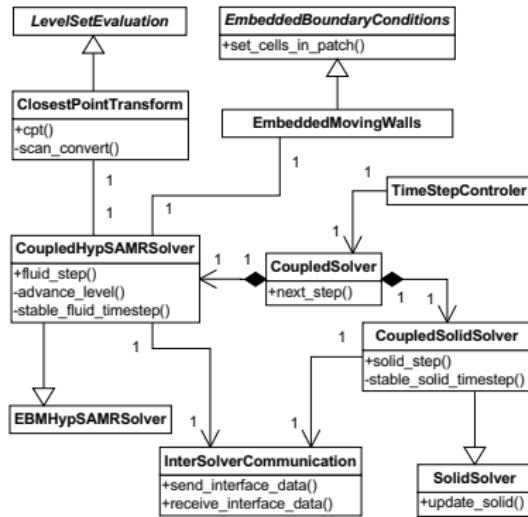


Eulerian/Lagrangian communication module

1. Put bounding boxes around each solid processors piece of the boundary and around each fluid processors grid
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3. Optimal point-to-point communication pattern, non-blocking

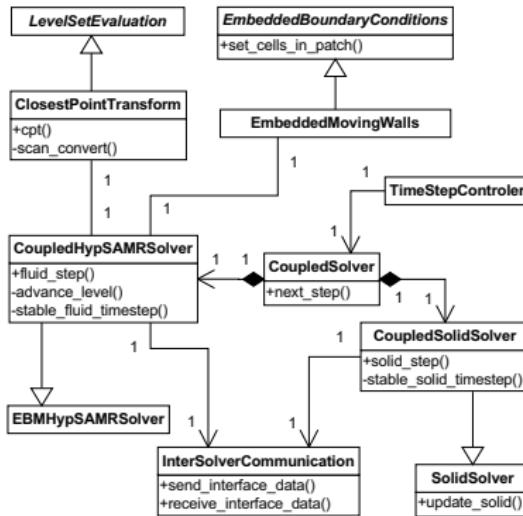


FSI coupling



- ▶ Coupling algorithm implemented in further derived HypSAMRSolver class
- ▶ Level set evaluation always with CPT algorithm
- ▶ Parallel communication through efficient non-blocking communication module ELC
- ▶ Time step selection for both solvers through CoupledSolver class

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- ▶ **AMRELCGFSolver<VectorType, FixupType, FlagType, dim >** is the derived AMRSolver<>class. [code/amroc/doc/html/amr/classAMRELCGFSolver.html](#)
- ▶ Uses the Eulerian interface of the Lagrangian communication routines [code/stlib/doc/html/elc/elc__page.html](#)
- ▶ and the closest point transform algorithm [code/stlib/doc/html/cpt/cpt__page.html](#) through the **CPTLevelSet<DataType, dim >** [code/amroc/doc/html/amr/classCPTLevelSet.html](#)

Lift-up of a spherical body

Cylindrical body hit by Mach 3 shockwave, 2D test case by
[Falcovitz et al., 1997]

Schlieren plot of density



Refinement levels



code/amroc/doc/html/apps/clawpack_2applications_2euler_22d_2SphereLiftOff_2src_2Problem_8h_source.html

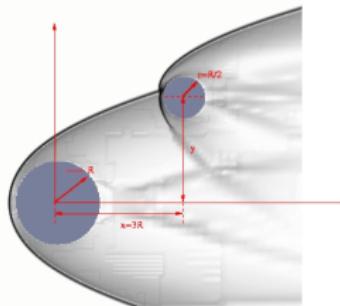
Proximal bodies in hypersonic flow

Flow modeled by Euler equations for a single polytropic gas with $p = (\gamma - 1) \rho e$

$$\partial_t \rho + \partial_{x_n}(\rho u_n) = 0, \quad \partial_t(\rho u_k) + \partial_{x_n}(\rho u_k u_n + \delta_{kn} p) = 0, \quad \partial_t(\rho E) + \partial_{x_n}(u_n(\rho E + p)) = 0$$

Numerical approximation with

- ▶ Finite volume flux-vector splitting scheme with MUSCL reconstruction, dimensional splitting



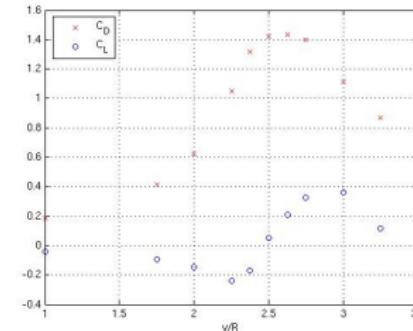
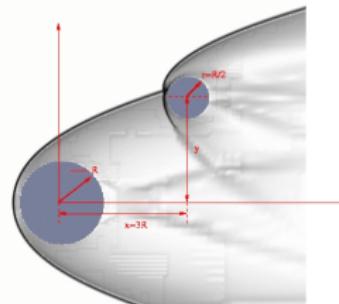
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Numerical approximation with

- ▶ Finite volume flux-vector splitting scheme with MUSCL reconstruction, dimensional splitting
- ▶ Spherical bodies, force computation with overlaid latitude-longitude mesh to obtain drag and lift coefficients $C_{D,L} = \frac{2F_{D,L}}{\rho v^2 \pi r^2}$
- ▶ inflow $M = 10$, C_D and C_L on secondary sphere, lateral position varied, no motion



Verification and validation

Static force measurements, $M = 10$:
[Laurence et al., 2007]

- Refinement study: $40 \times 40 \times 32$ base grid ,
up to without AMR up to $\sim 209.7 \cdot 10^6$
cells, largest run $\sim 35,000$ h CPU

I_{\max}	C_D	ΔC_D	C_L	ΔC_L
1	1.264		-0.176	
2	1.442	0.178	-0.019	0.157
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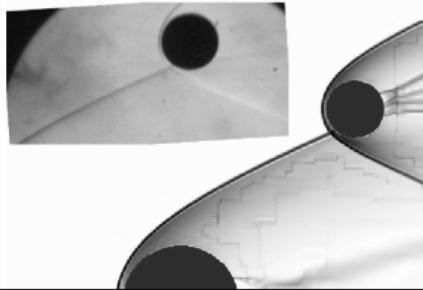
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- Comparison with experimental results: 3 additional levels, ~ 2000 h CPU

	Experimental	Computational
C_D	1.11 ± 0.08	1.01
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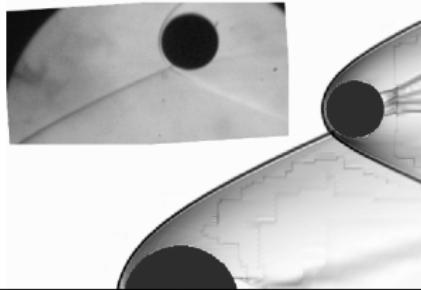
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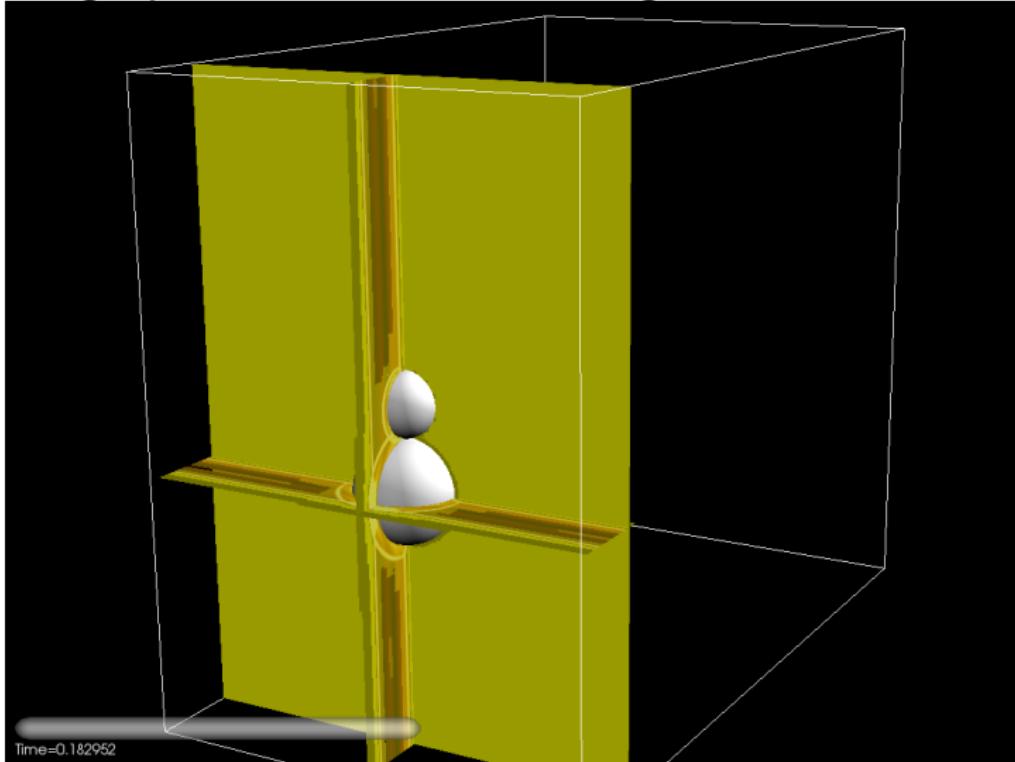
Dynamic motion, $M = 4$:

- Base grid $150 \times 125 \times 90$, two additional levels with $r_{1,2} = 2$
- 24,704 time steps, 36,808 h CPU on 256 cores IBM BG/P



[Laurence and Deiterding, 2011]

Schlieren graphics on refinement regions



code/amroc/doc/html/apps/clawpack_2applications_2euler_23d_2Spheres_2src_2Problem_8h_source.html

Treatment of thin structures

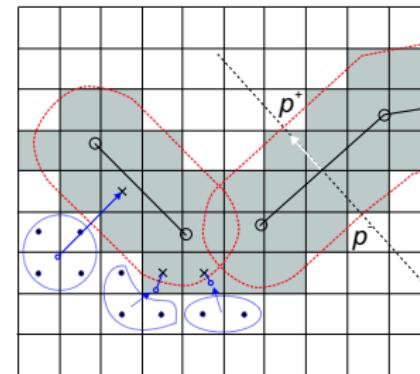
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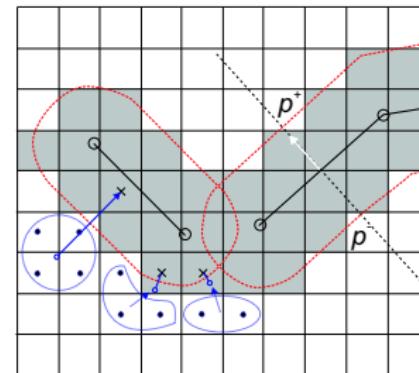
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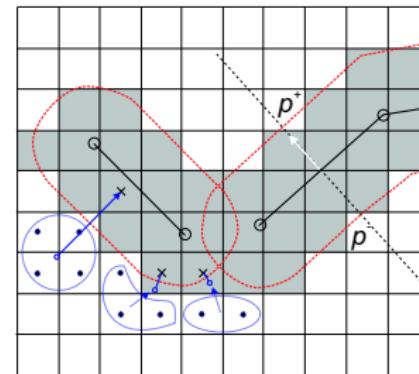
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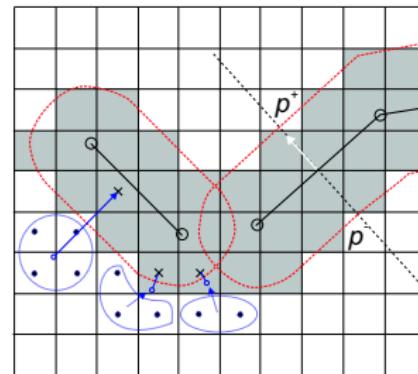
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- ▶ Utilize finite difference solver using the beam equation



$$\rho_s h \frac{\partial^2 w}{\partial t^2} + EI \frac{\partial^4 w}{\partial \bar{x}^4} = p^F$$

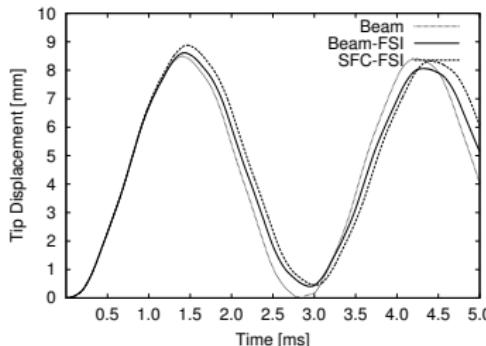
to verify FSI algorithms

FSI verification by elastic vibration

- ▶ Thin steel plate (thickness $h = 1$ mm, length 50 mm), clamped at lower end
- ▶ $\rho_s = 7600 \text{ kg/m}^3$, $E = 220 \text{ GPa}$, $I = h^3/12$, $\nu = 0.3$
- ▶ Modeled with beam solver (101 points) and thin-shell FEM solver (325 triangles) by F. Cirak

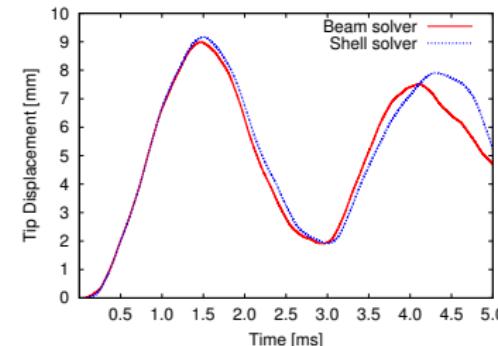
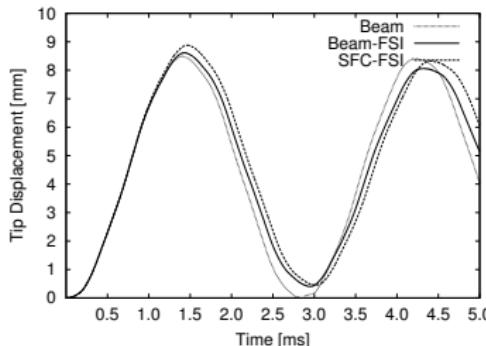
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- ▶ Left: Coupling verification with constant instantaneous loading by $\Delta p = 100 \text{ kPa}$



FSI verification by elastic vibration

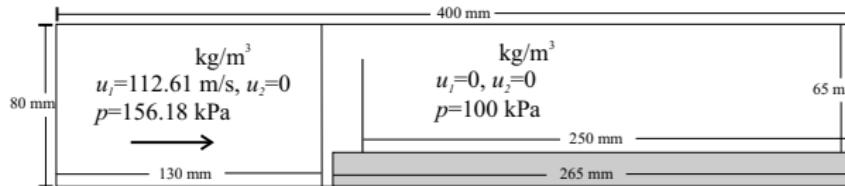
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- ▶ Left: Coupling verification with constant instantaneous loading by $\Delta p = 100 \text{ kPa}$
- ▶ Right: FSI verification with Mach 1.21 shockwave in air ($\gamma = 1.4$)



Shock-driven elastic panel motion

Test case suggested by [Giordano et al., 2005]

- ▶ Forward facing step geometry, fixed walls everywhere except at inflow

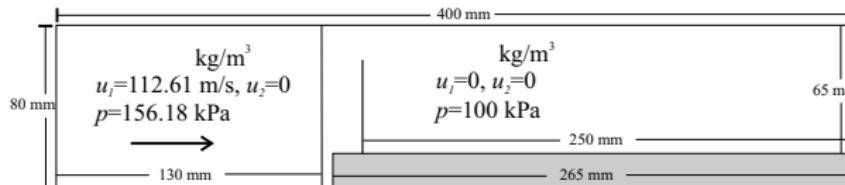


- ▶ SAMR base mesh $320 \times 64(\times 2)$, $r_{1,2} = 2$

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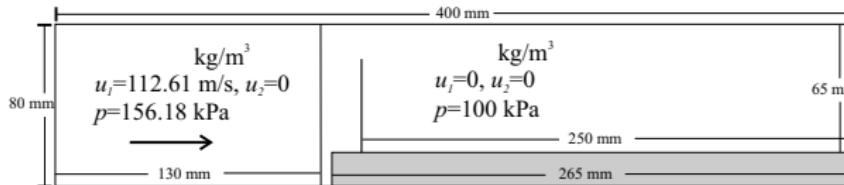


- ▶ SAMR base mesh $320 \times 64 (\times 2)$, $r_{1,2} = 2$
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code/doc/html/capps/beam-amroc_2VibratingBeam_2src_2FluidProblem_8h_source.html,
code/doc/html/capps/beam-amroc_2VibratingBeam_2src_2SolidProblem_8h_source.html
 - ▶ FEM-FSI: 322 h CPU on 14 fluid CPU + 2 solid CPU
code/doc/html/capps/sfc-amroc_2VibratingPanel_2src_2FluidProblem_8h_source.html,
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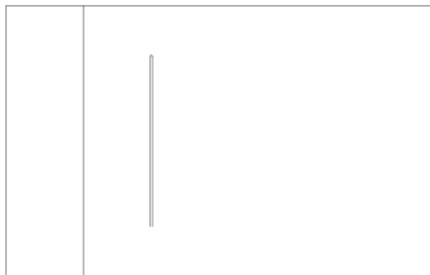
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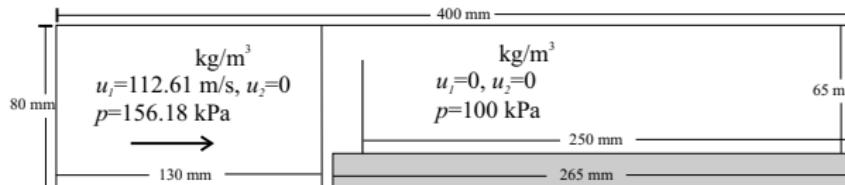
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code/doc/html/capps/beam-amroc_2VibratingBeam_2src_2SolidProblem_8h_source.html
 - ▶ FEM-FSI: 322 h CPU on 14 fluid CPU + 2 solid CPU
code/doc/html/capps/sfc-amroc_2VibratingPanel_2src_2FluidProblem_8h_source.html,
code/doc/html/capps/VibratingPanel_2src_2ShellManagerSpecific_8h_source.html



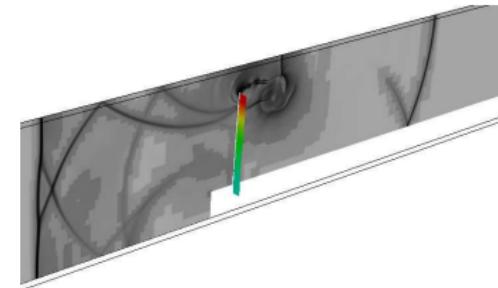
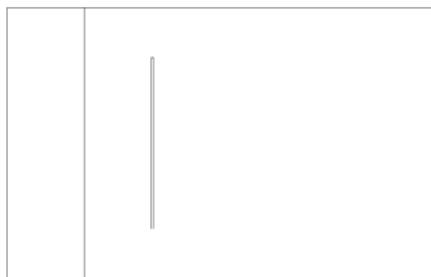
Shock-driven elastic panel motion

Test case suggested by [Giordano et al., 2005]

- ▶ Forward facing step geometry, fixed walls everywhere except at inflow



- ▶ SAMR base mesh $320 \times 64 (\times 2)$, $r_{1,2} = 2$
- ▶ Intel 3.4GHz Xeon dual processors, GB Ethernet interconnect
 - ▶ Beam-FSI: 12.25 h CPU on 3 fluid CPU + 1 solid CPU
code/doc/html/capps/beam-amroc_2VibratingBeam_2src_2FluidProblem_8h_source.html,
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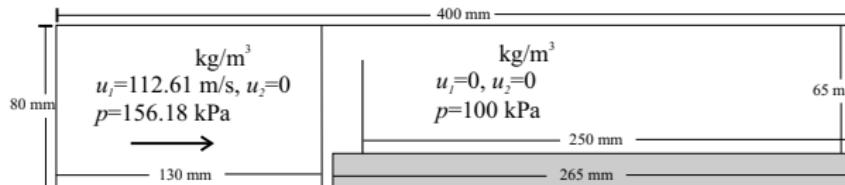


$t = 0.43$ ms after impact

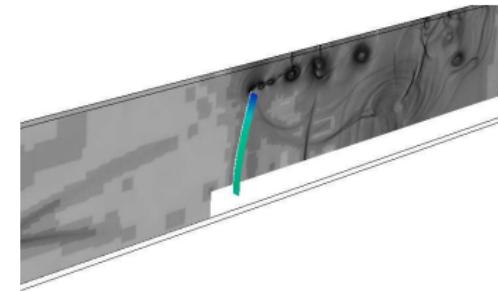
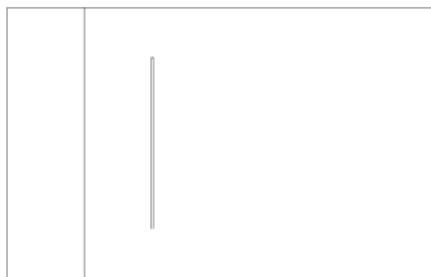
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code/doc/html/capps/VibratingPanel_2src_2ShellManagerSpecific_8h_source.html



$t = 1.56$ ms after impact

Detonation-driven plastic deformation

Chapman-Jouguet detonation in a tube filled with a stoichiometric ethylene and oxygen ($C_2H_4 + 3 O_2$, 295 K) mixture. Euler equations with single exothermic reaction $A \longrightarrow B$

$$\partial_t \rho + \partial_{x_n} (\rho u_n) = 0 , \quad \partial_t (\rho u_k) + \partial_{x_n} (\rho u_k u_n + \delta_{kn} p) = 0 , k = 1, \dots, d$$

$$\partial_t (\rho E) + \partial_{x_n} (u_n (\rho E + p)) = 0 , \quad \partial_t (Y\rho) + \partial_{x_n} (Y\rho u_n) = \psi$$

with

$$p = (\gamma - 1)(\rho E - \frac{1}{2}\rho u_n u_n - \rho Y q_0) \quad \text{and} \quad \psi = -k Y \rho \exp\left(\frac{-E_A \rho}{p}\right)$$

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modeled with heuristic detonation model by

[Mader, 1979]

$$V := \rho^{-1}, \quad V_0 := \rho_0^{-1}, \quad V_{CJ} := \rho_{CJ}$$

$$Y' := 1 - (V - V_0)/(V_{CJ} - V_0)$$

If $0 \leq Y' \leq 1$ and $Y > 10^{-8}$ then

If $Y < Y'$ and $Y' < 0.9$ then $Y' := 0$

If $Y' < 0.99$ then $p' := (1 - Y')\rho_{CJ}$

else $p' := p$

$$\rho_A := Y' \rho$$

$$E := p' / (\rho(\gamma - 1)) + Y' q_0 + \frac{1}{2} u_n u_n$$

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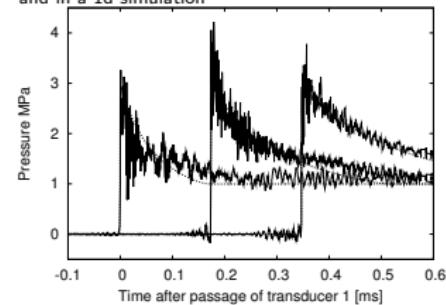
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Comparison of the pressure traces in the experiment and in a 1d simulation



Tube with flaps

► Fluid: VanLeer FVS

- Detonation model with $\gamma = 1.24$, $p_{\text{CJ}} = 3.3 \text{ MPa}$, $D_{\text{CJ}} = 2376 \text{ m/s}$
- AMR base level: $104 \times 80 \times 242$, $r_{1,2} = 2$, $r_3 = 4$
- $\sim 4 \cdot 10^7$ cells instead of $7.9 \cdot 10^9$ cells (uniform)
- Tube and detonation fully refined
- Thickening of 2D mesh: 0.81 mm on both sides (real 0.445 mm)

Tube with flaps

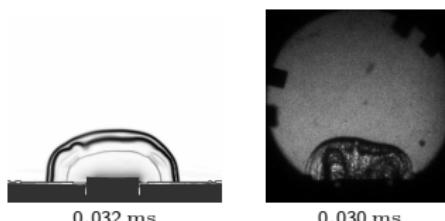
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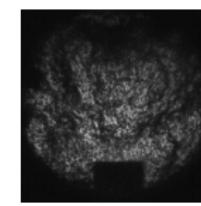
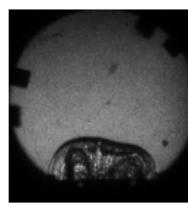
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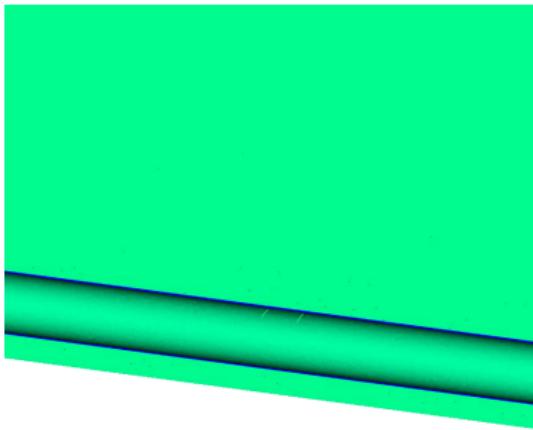


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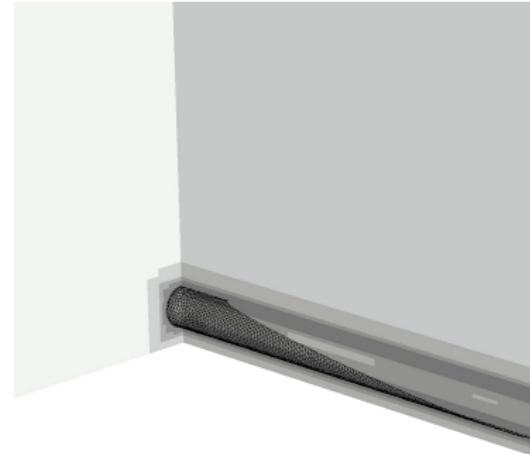
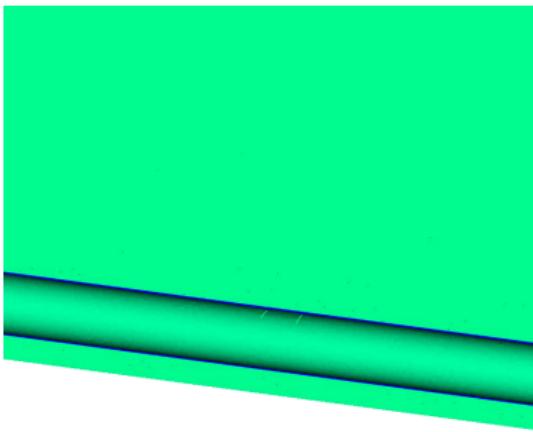


Tube with flaps: results



Fluid density and displacement in y-
direction in solid

Tube with flaps: results



Fluid density and displacement in y-direction in solid

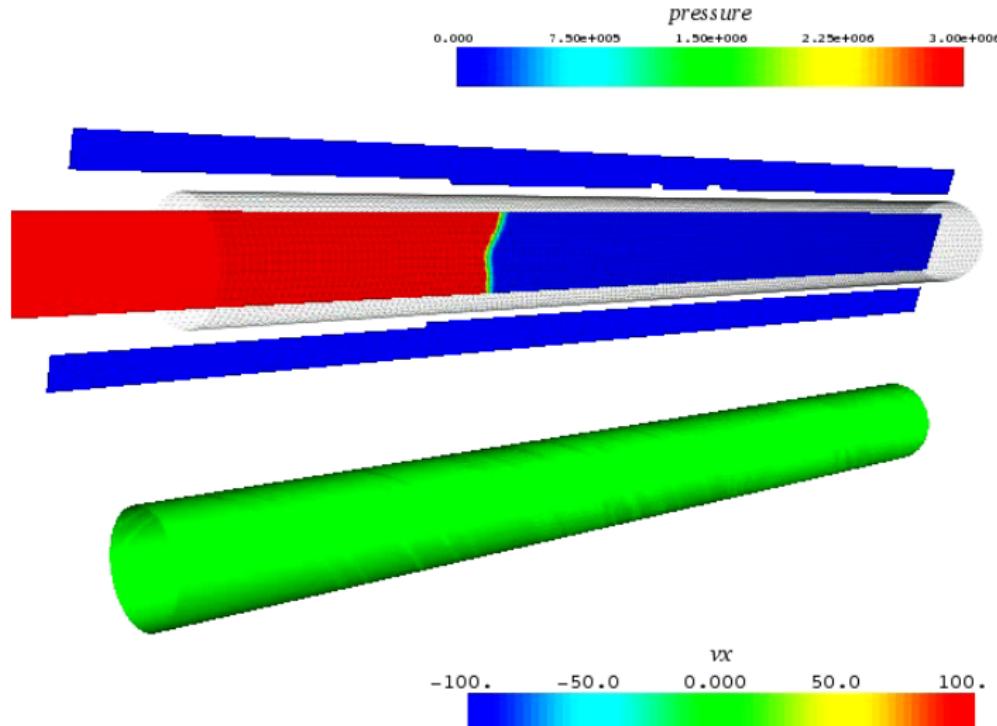
Schlieren plot of fluid density on refinement levels

[Cirak et al., 2007]

code/doc/html/capps/sfc-amroc_2TubeCJBurnFlaps_2src_2FluidProblem_8h_source.html,

code/doc/html/capps/TubeCJBurnFlaps_2src_2ShellManagerSpecific_8h_source.html

Coupled fracture simulation



code/doc/html/capps/sfc-amroc_2TubeCJBurnFrac_2src_2FluidProblem_8h_source.html,
code/doc/html/capps/TubeCJBurnFrac_2src_2ShellManagerSpecific_8h_source.html

Underwater explosion modeling

Volume fraction based two-component model with $\sum_{i=1}^m \alpha^i = 1$, that defines mixture quantities as

$$\rho = \sum_{i=1}^m \alpha^i \rho^i, \quad \rho u_n = \sum_{i=1}^m \alpha^i \rho^i u_n^i, \quad \rho e = \sum_{i=1}^m \alpha^i \rho^i e^i$$

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and the overall set of equations [Shyue, 1998]

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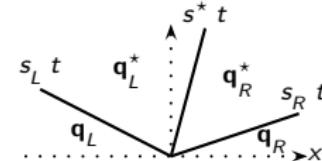
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Oscillation free at contacts: [Abgrall and Karni, 2001][Shyue, 2006]

Approximate Riemann solver

Use HLLC approach because of robustness and positivity preservation

$$\mathbf{q}^{HLLC}(x_1, t) = \begin{cases} \mathbf{q}_L, & x_1 < s_L t, \\ \mathbf{q}_L^*, & s_L t \leq x_1 < s^* t, \\ \mathbf{q}_R^*, & s^* t \leq x_1 \leq s_R t, \\ \mathbf{q}_R, & x_1 > s_R t, \end{cases}$$



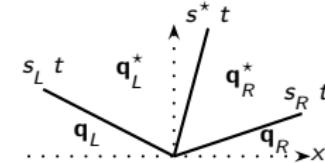
Wave speed estimates [Davis, 1988] $s_L = \min\{u_{1,L} - c_L, u_{1,R} - c_R\}$,

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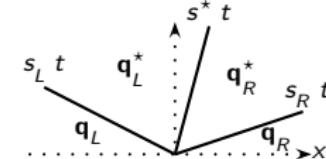
Unknown state [Toro et al., 1994]

$$s^* = \frac{p_R - p_L + s_L u_{1,L} (s_L - u_{1,L}) - \rho_R u_{1,R} (s_R - u_{1,R})}{\rho_L (s_L - u_{1,L}) - \rho_R (s_R - u_{1,R})}$$

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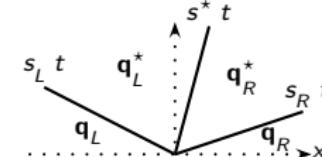
$$\mathbf{q}_\tau^* = \left[\eta, \eta s^*, \eta u_2, \eta \left[\frac{(\rho E)_\tau}{\rho_\tau} + (s^* - u_{1,\tau}) \left(s_\tau + \frac{p_\tau}{\rho_\tau (s_\tau - u_{1,\tau})} \right) \right], \frac{1}{\gamma_\tau - 1}, \frac{\gamma_\tau p_{\infty,\tau}}{\gamma_\tau - 1} \right]^T$$

$$\eta = \rho_\tau \frac{s_\tau - u_{1,\tau}}{s_\tau - s^*}, \quad \tau = \{L, R\}$$

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$$\eta = \rho_\tau \frac{s_\tau - u_{1,\tau}}{s_\tau - s^*}, \quad \tau = \{L, R\}$$

Evaluate waves as $\mathcal{W}_1 = \mathbf{q}_L^* - \mathbf{q}_L$, $\mathcal{W}_2 = \mathbf{q}_R^* - \mathbf{q}_L^*$, $\mathcal{W}_3 = \mathbf{q}_R - \mathbf{q}_R^*$ and $\lambda_1 = s_L$,

$\lambda_2 = s^*$, $\lambda_3 = s_R$ to compute the fluctuations $\mathcal{A}^- \Delta = \sum_{\lambda_\nu < 0} \lambda_\nu \mathcal{W}_\nu$,

$\mathcal{A}^+ \Delta = \sum_{\lambda_\nu \geq 0} \lambda_\nu \mathcal{W}_\nu$ for $\nu = \{1, 2, 3\}$

Overall scheme: Wave Propagation method [Shyue, 2006]

Underwater explosion FSI simulations

- ▶ Air: $\gamma^A = 1.4$, $p_\infty^A = 0$, $\rho^A = 1.29 \text{ kg/m}^3$
- ▶ Water: $\gamma^W = 7.415$, $p_\infty^W = 296.2 \text{ MPa}$, $\rho^W = 1027 \text{ kg/m}^3$

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- ▶ 3D simulation of deformation of air backed aluminum plate with $r = 85 \text{ mm}$, $h = 3 \text{ mm}$ from underwater explosion
 - ▶ Water basin [Ashani and Ghamsari, 2008] $2 \text{ m} \times 1.6 \text{ m} \times 2 \text{ m}$
 - ▶ Explosion modeled as energy increase ($m_{\text{C4}} \cdot 6.06 \text{ MJ/kg}$) in sphere with $r=5\text{mm}$
 - ▶ $\rho_s = 2719 \text{ kg/m}^3$, $E = 69 \text{ GPa}$, $\nu = 0.33$, J2 plasticity model, yield stress $\sigma_y = 217.6 \text{ MPa}$

Underwater explosion FSI simulations

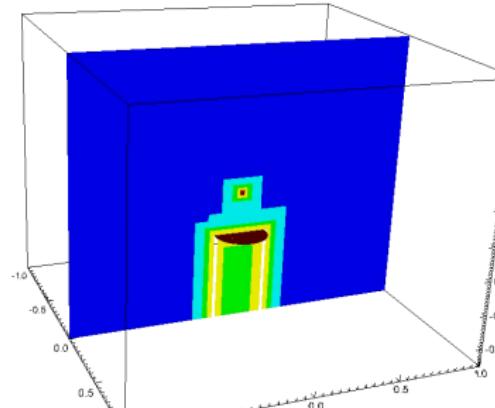
- ▶ Air: $\gamma^A = 1.4$, $p_\infty^A = 0$, $\rho^A = 1.29 \text{ kg/m}^3$
- ▶ Water: $\gamma^W = 7.415$, $p_\infty^W = 296.2 \text{ MPa}$, $\rho^W = 1027 \text{ kg/m}^3$
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- ▶ 3D simulation of copper plate $r = 32 \text{ mm}$, $h = 0.25 \text{ mm}$ rupturing due to water hammer
 - ▶ Water-filled shocktube 1.3 m with driver piston [Deshpande et al., 2006]
 - ▶ Piston simulated with separate level set, see [Deiterding et al., 2009] for pressure wave
 - ▶ $\rho_s = 8920 \text{ kg/m}^3$, $E = 130 \text{ GPa}$, $\nu = 0.31$, J2 plasticity model, $\sigma_y = 38.5 \text{ MPa}$, cohesive interface model, max. tensile stress $\sigma_c = 525 \text{ MPa}$

Underwater explosion simulation

- ▶ AMR base grid $50 \times 40 \times 50$, $r_{1,2,3} = 2$, $r_4 = 4$, $I_c = 3$, highest level restricted to initial explosion center, 3rd and 4th level to plate vicinity
- ▶ Triangular mesh with 8148 elements
- ▶ Computations of 1296 coupled time steps to $t_{end} = 1\text{ ms}$
- ▶ 10+2 nodes 3.4 GHz Intel Xeon dual processor, $\sim 130\text{ h CPU}$

Maximal deflection [mm]

	Exp.	Sim.
20 g, $d = 25\text{ cm}$	28.83	25.88
30 g, $d = 30\text{ cm}$	30.09	27.31



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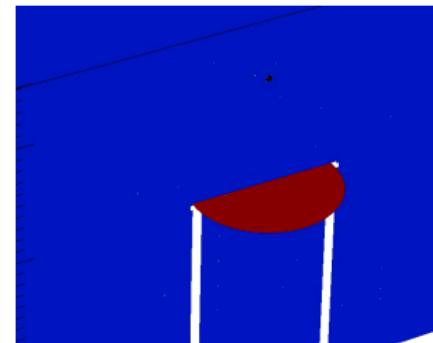
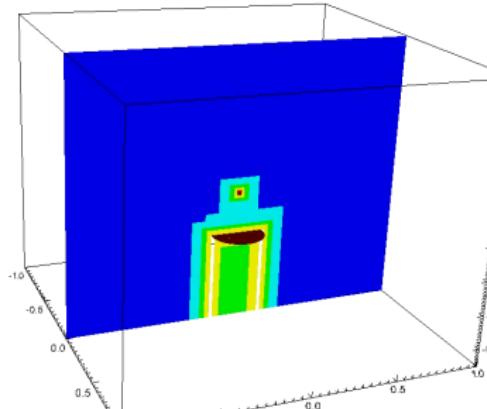
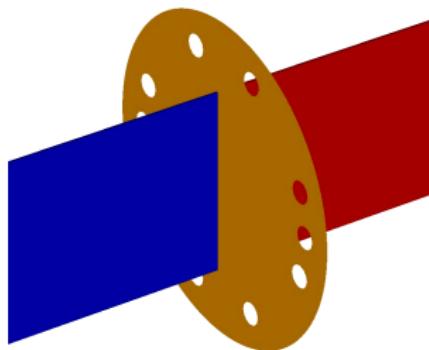


Plate in underwater shocktube

- ▶ AMR base mesh $374 \times 20 \times 20$, $r_{1,2} = 2$, $I_c = 2$, solid mesh: 8896 triangles
- ▶ ~ 1250 coupled time steps to $t_{end} = 1$ ms
- ▶ 6+6 nodes 3.4 GHz Intel Xeon dual processor, ~ 800 h CPU

code/doc/html/capps/sfc-amroc_2WaterBlastFracture_2src_2FluidProblem_8h_source.html,
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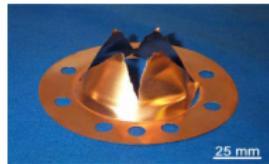
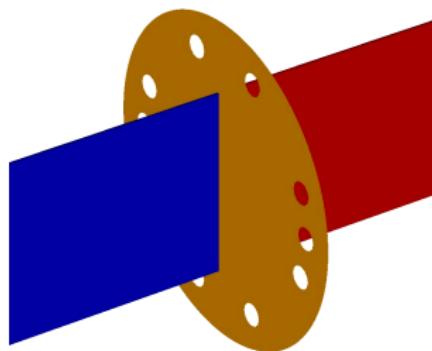


$$p_0 = 64 \text{ MPa}$$

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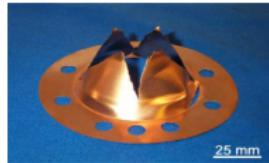
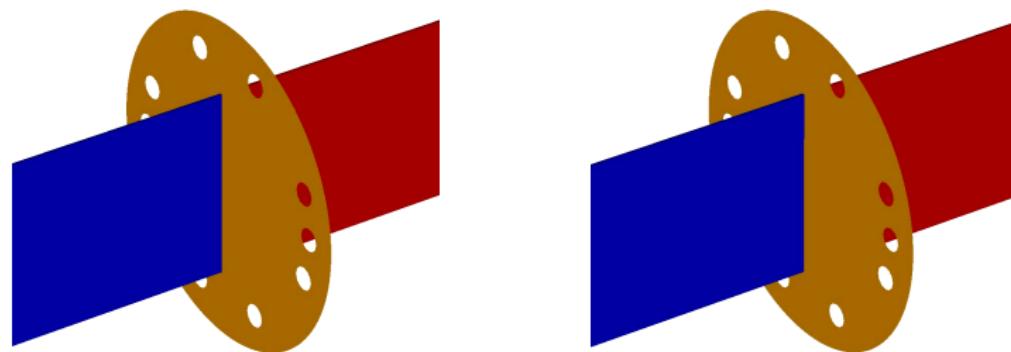


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Deformation from water hammer

Plate in underwater shocktube

- ▶ AMR base mesh $374 \times 20 \times 20$, $r_{1,2} = 2$, $I_c = 2$, solid mesh: 8896 triangles
- ▶ ~ 1250 coupled time steps to $t_{end} = 1$ ms
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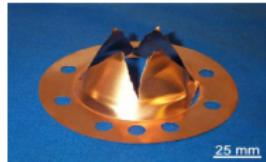
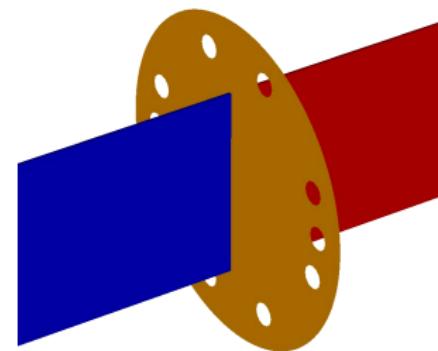
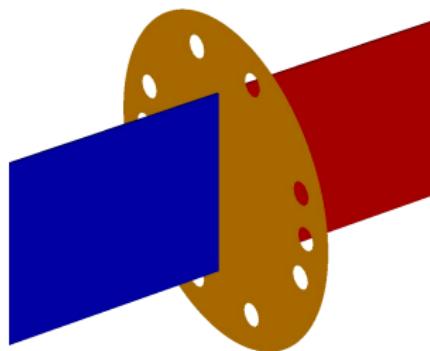
$$p_0 = 64 \text{ MPa}$$

$$p_0 = 173 \text{ MPa}$$

Plate in underwater shocktube

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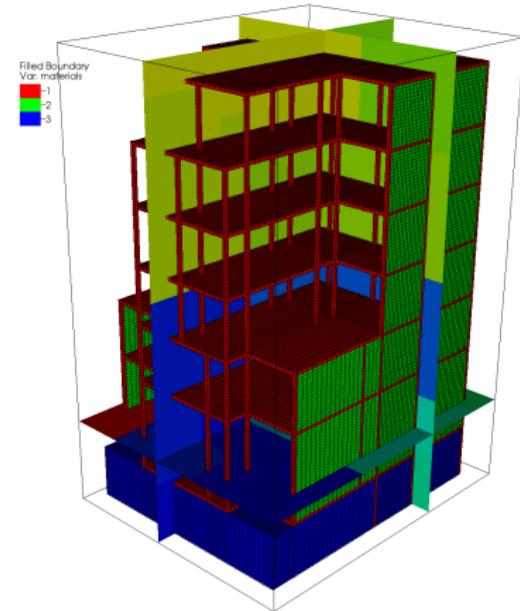
$p_0 = 64$ MPa



$p_0 = 173$ MPa

Blast explosion in a multistory building

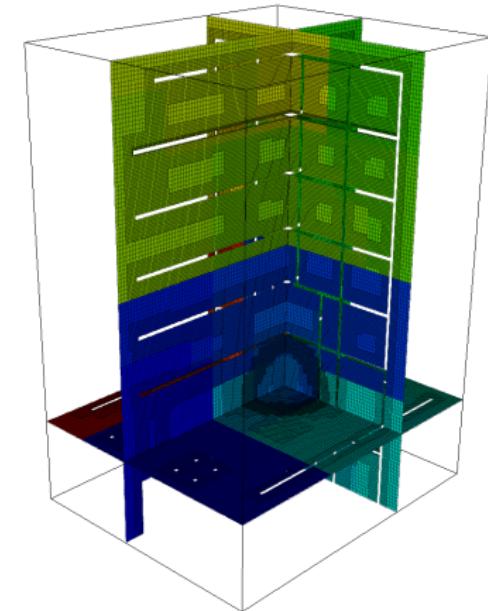
- ▶ 20 m × 40 m × 25 m seven-story building similar to [Luccioni et al., 2004]
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- ▶ SAMR: $80 \times 120 \times 90$ base level, three additional levels $r_{1,2} = 2$, $l_{\text{fsi}} = 1$, $k = 1$
- ▶ Simulation with ground: 1,070 coupled time steps, 830 h CPU (~ 25.9 h wall time) on 31+1 cores
- ▶ $\sim 8,000,000$ cells instead of 55,296,000 (uniform)
- ▶ 69,709 hexahedral elements and with material parameters. [Deiterding and Wood, 2013]



	ρ_s [kg/m ³]	σ_0 [MPa]	E_T [GPa]	β	K [GPa]	G [GPa]	$\bar{\epsilon}^P$	p_f [MPa]
Columns	2010	50	11.2	1.0	21.72	4.67	0.02	-30
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Blast explosion in a multistory building

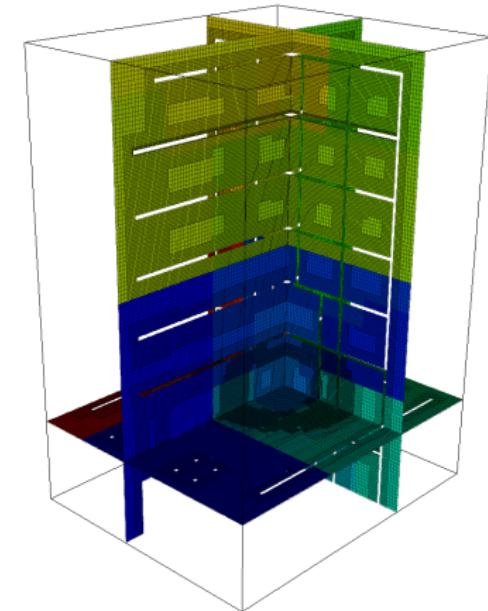
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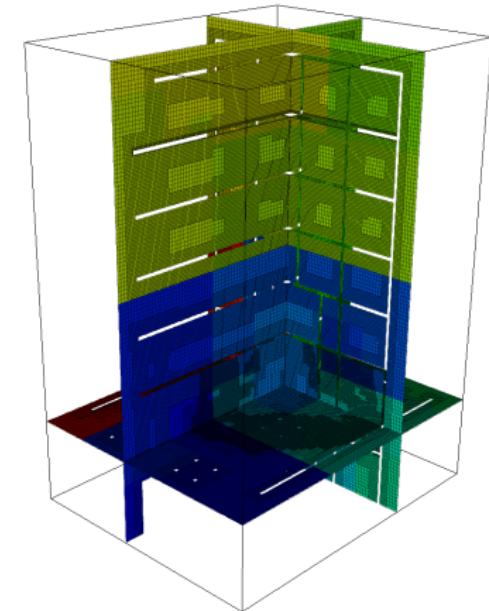
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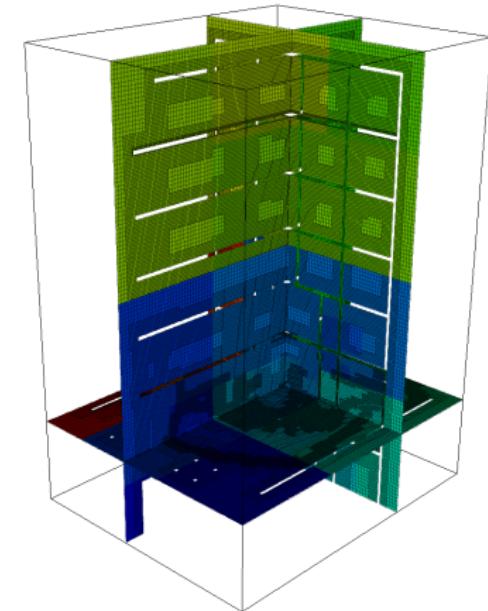
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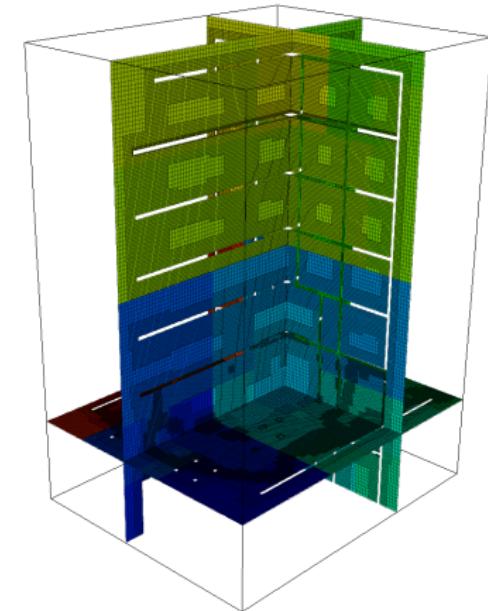
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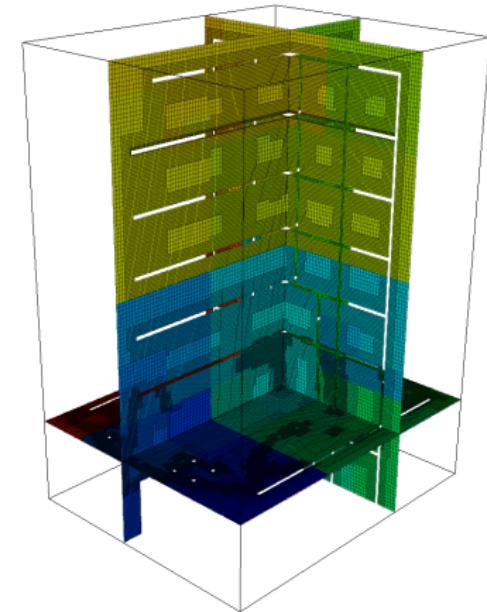
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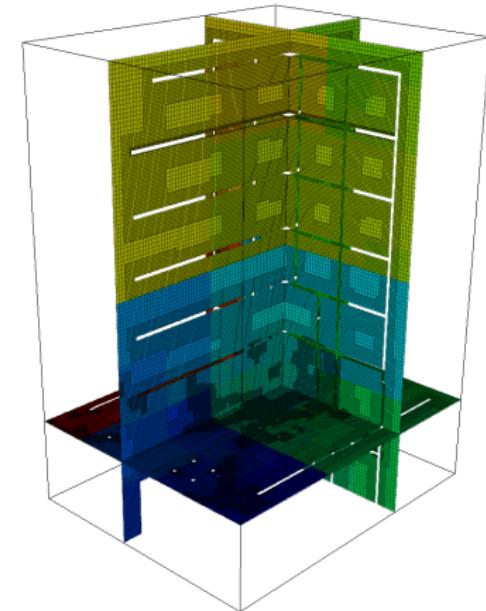
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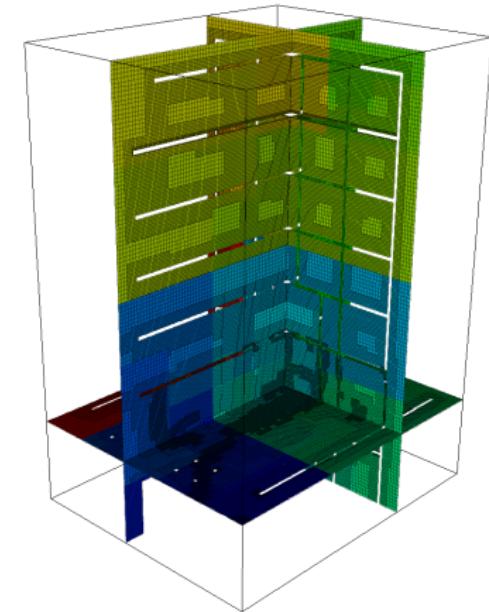
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Blast explosion in a multistory building

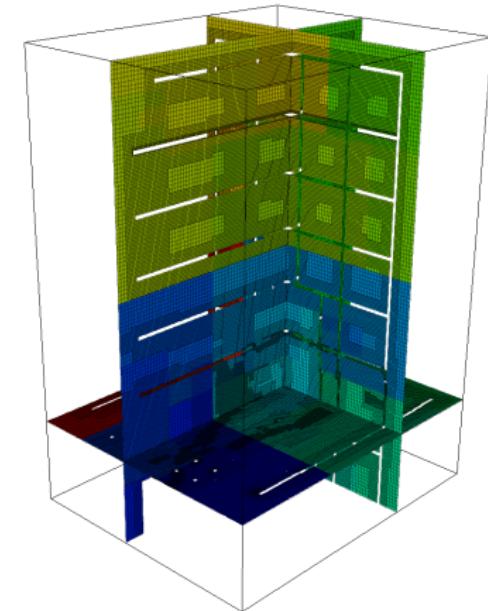
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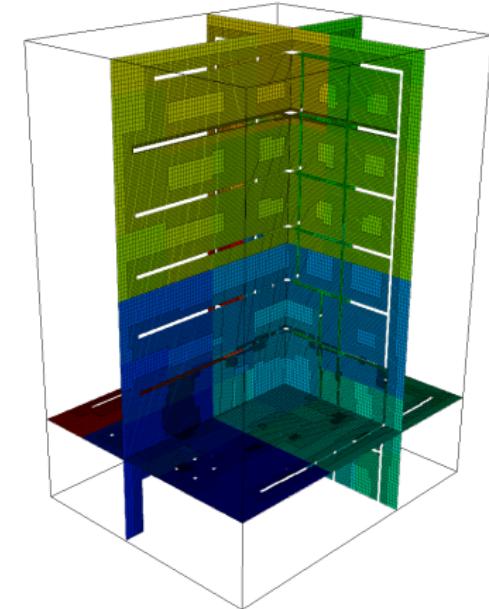
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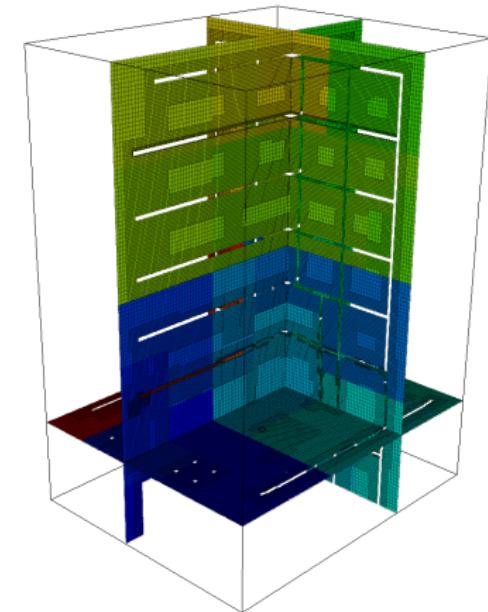
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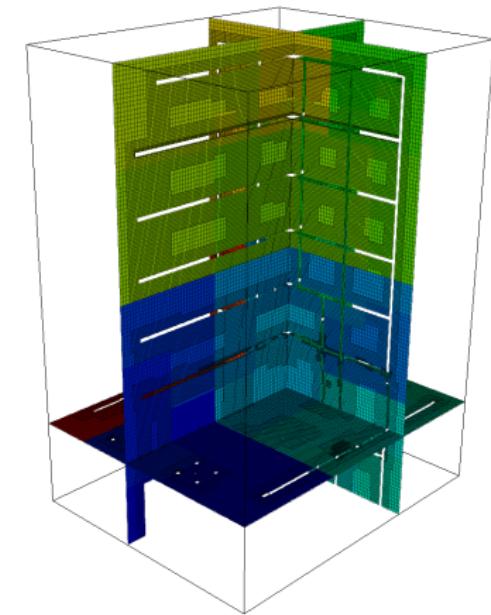
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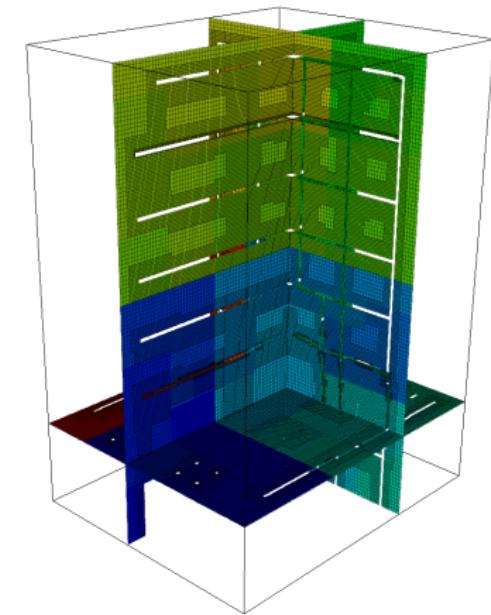
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	ρ_s [kg/m ³]	σ_0 [MPa]	E_T [GPa]	β	K [GPa]	G [GPa]	$\bar{\epsilon}^P$	p_f [MPa]
Columns	2010	50	11.2	1.0	21.72	4.67	0.02	-30
Walls	2010	25	11.2	1.0	6.22	4.67	0.01	-15

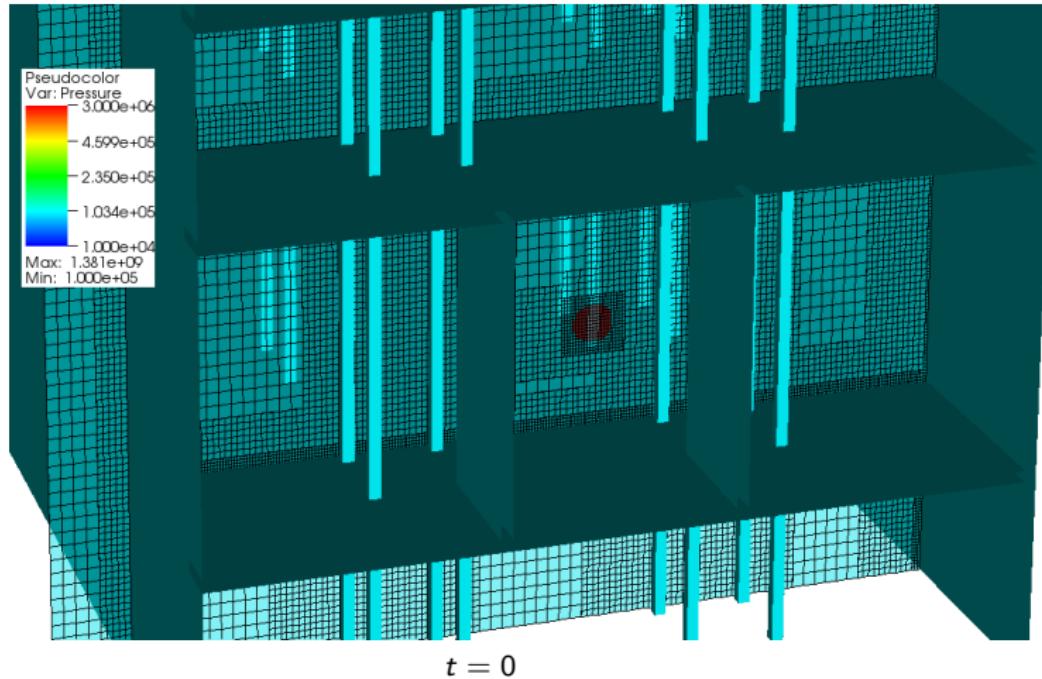
Blast explosion in a multistory building

- ▶ 20 m × 40 m × 25 m seven-story building similar to [Lucchini et al., 2004]
- ▶ Spherical energy deposition $\equiv 400 \text{ kg TNT}$, $r = 0.5 \text{ m}$ in lobby of building
- ▶ SAMR: 80 × 120 × 90 base level, three additional levels $r_{1,2} = 2$, $I_{fsi} = 1$, $k = 1$
- ▶ Simulation with ground: 1,070 coupled time steps, 830 h CPU (~ 25.9 h wall time) on 31+1 cores
- ▶ $\sim 8,000,000$ cells instead of 55,296,000 (uniform)
- ▶ 69,709 hexahedral elements and with material parameters. [Deiterding and Wood, 2013]

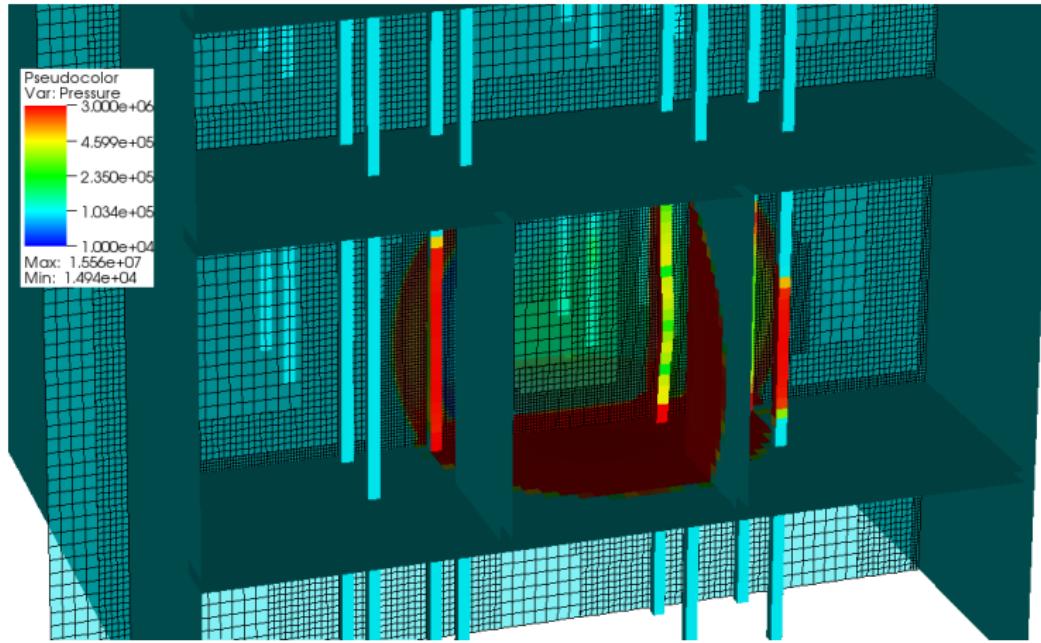


	ρ_s [kg/m ³]	σ_0 [MPa]	E_T [GPa]	β	K [GPa]	G [GPa]	$\bar{\epsilon}^P$	p_f [MPa]
Columns	2010	50	11.2	1.0	21.72	4.67	0.02	-30
Walls	2010	25	11.2	1.0	6.22	4.67	0.01	-15

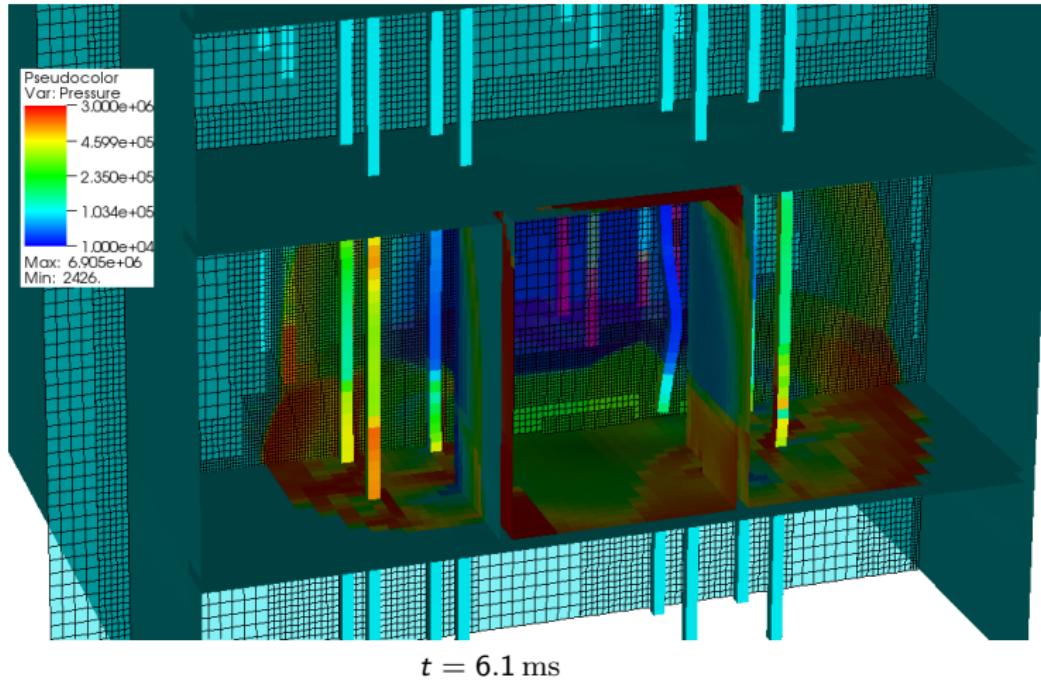
Blast explosion in a multistory building – II



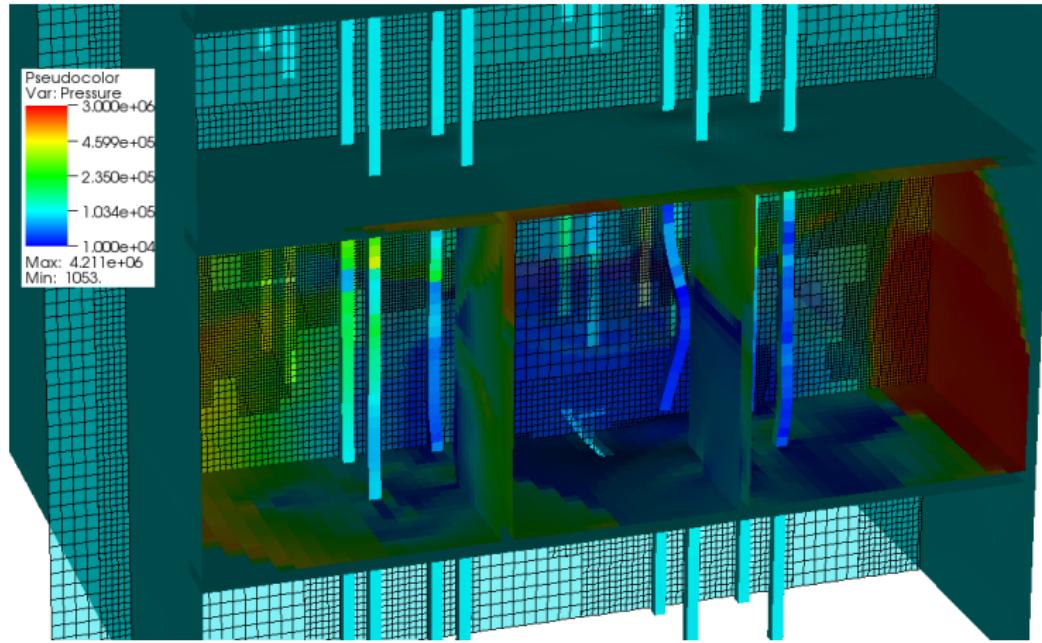
Blast explosion in a multistory building – II



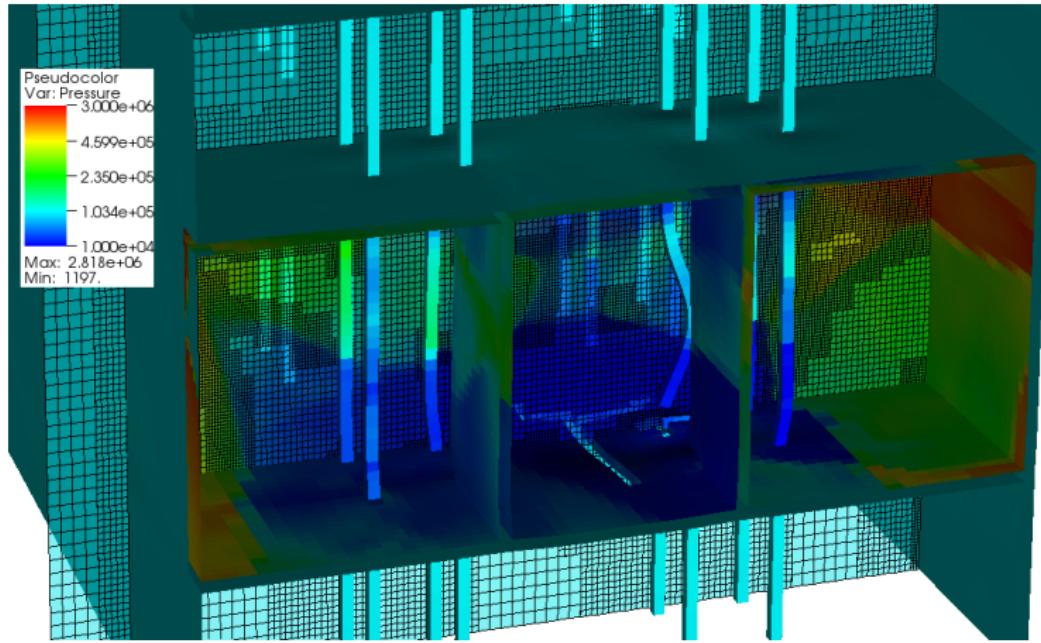
Blast explosion in a multistory building – II



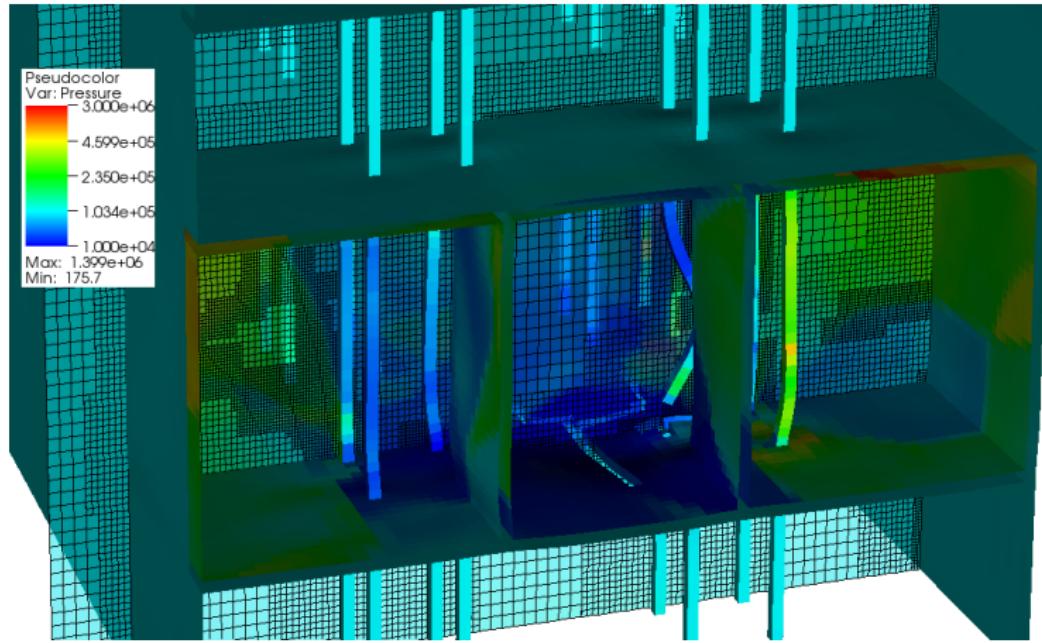
Blast explosion in a multistory building – II



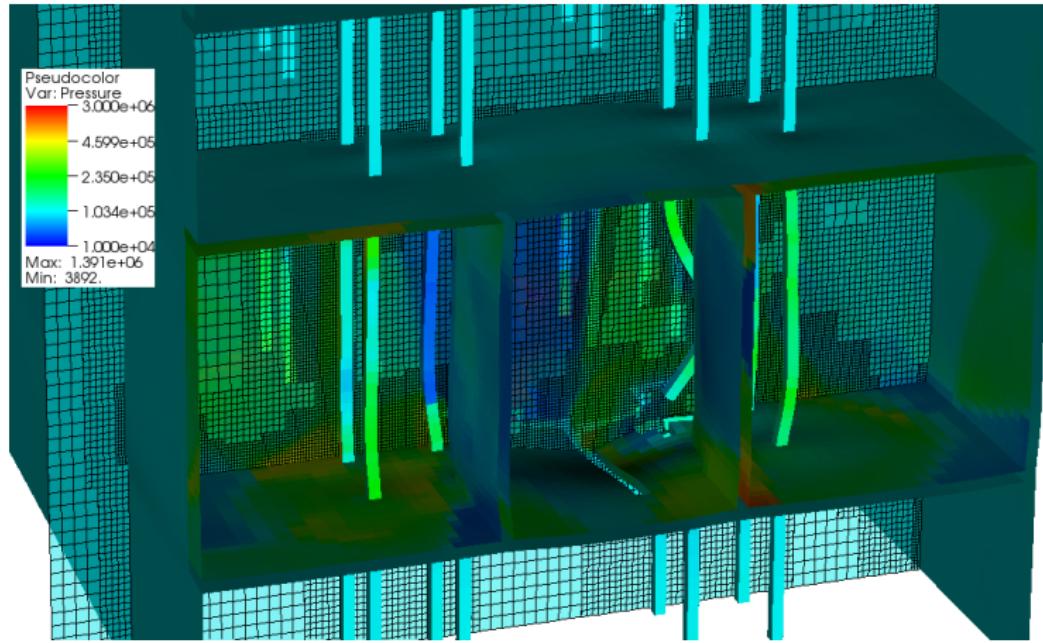
Blast explosion in a multistory building – II



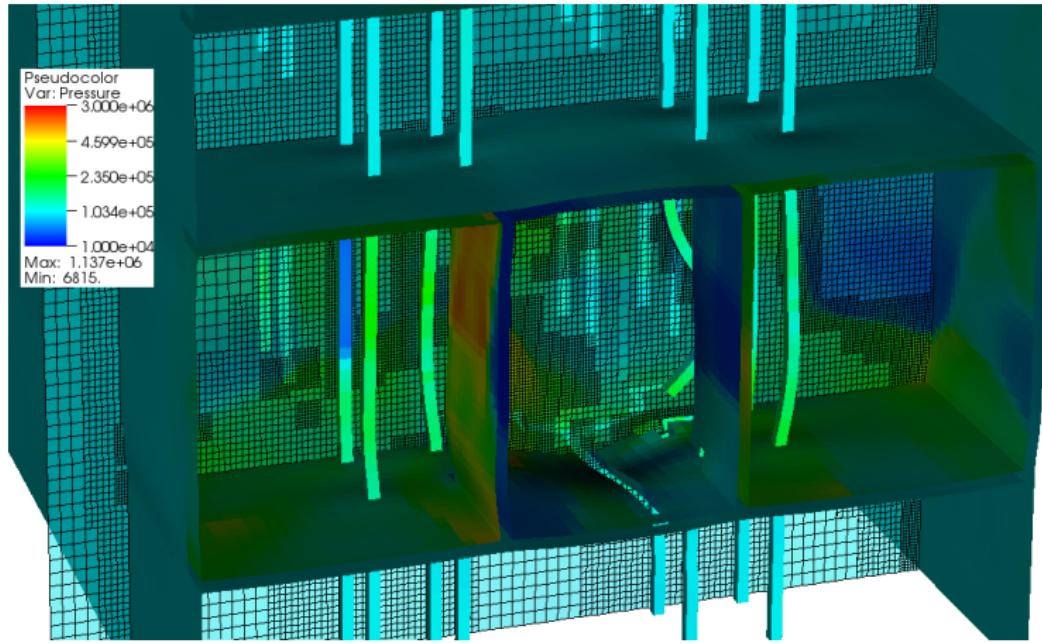
Blast explosion in a multistory building – II



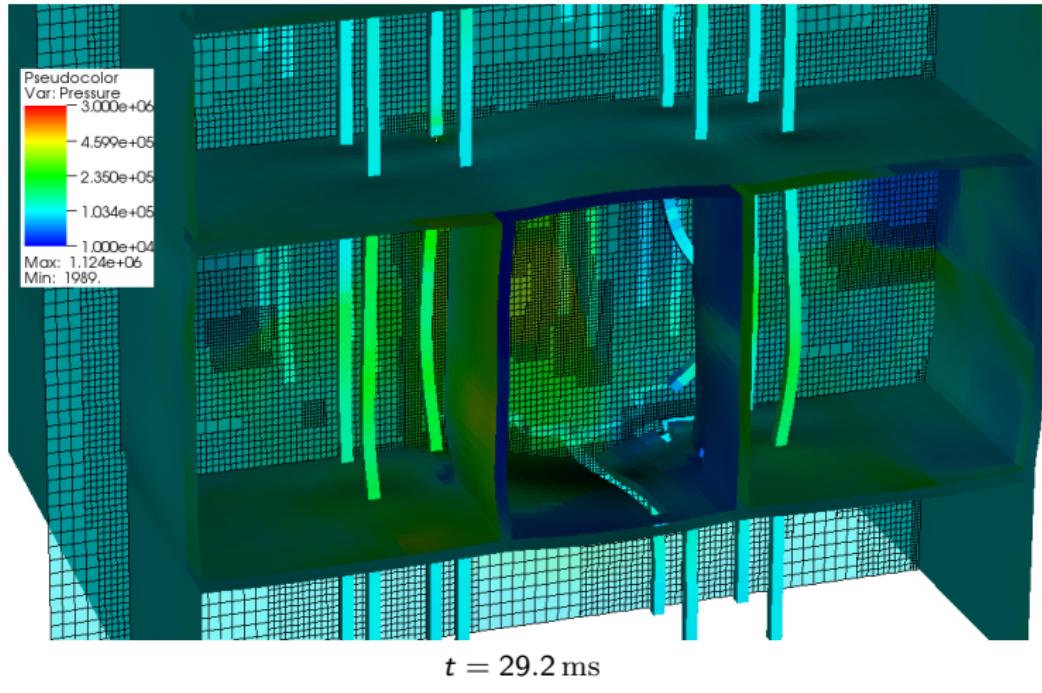
Blast explosion in a multistory building – II



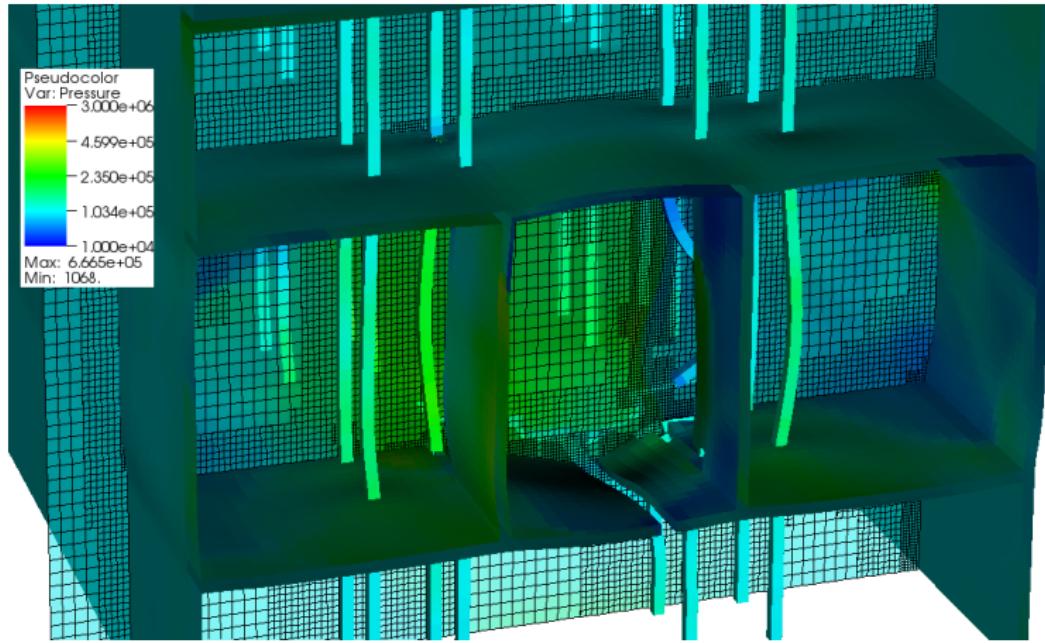
Blast explosion in a multistory building – II



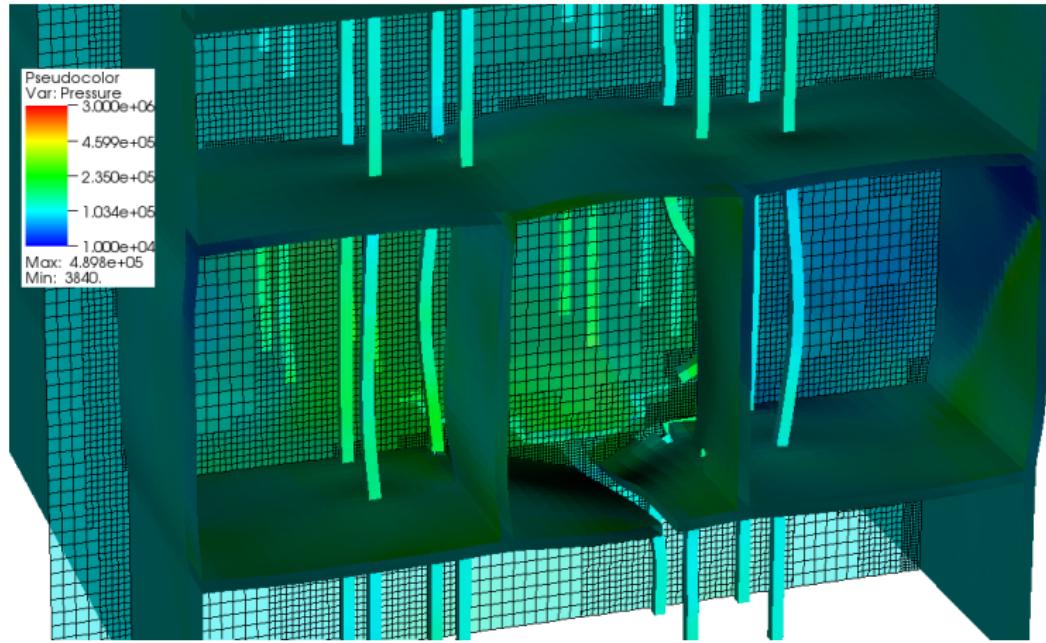
Blast explosion in a multistory building – II



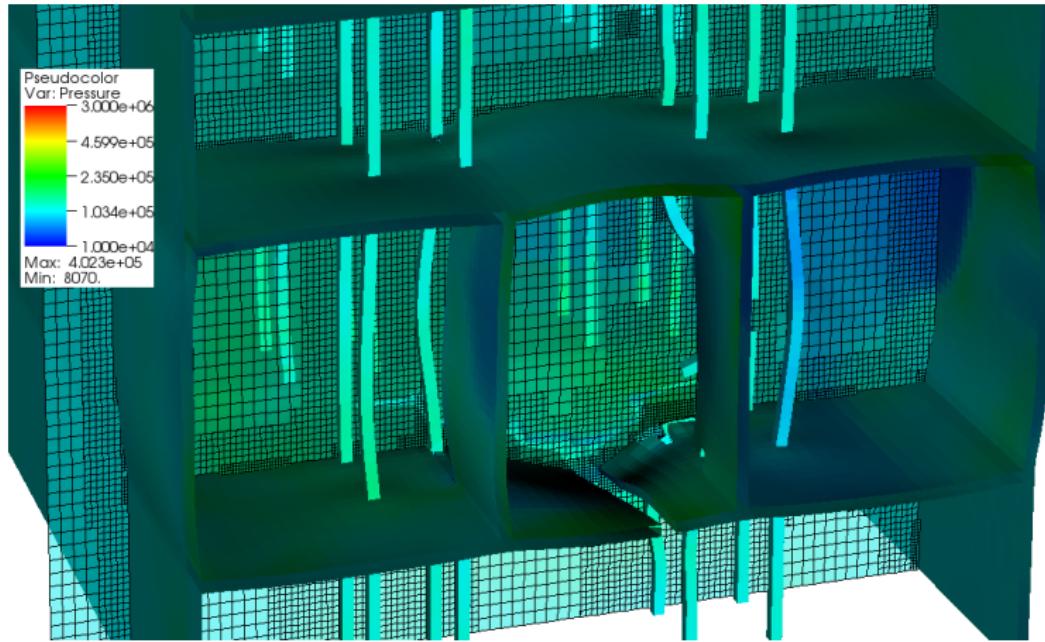
Blast explosion in a multistory building – II



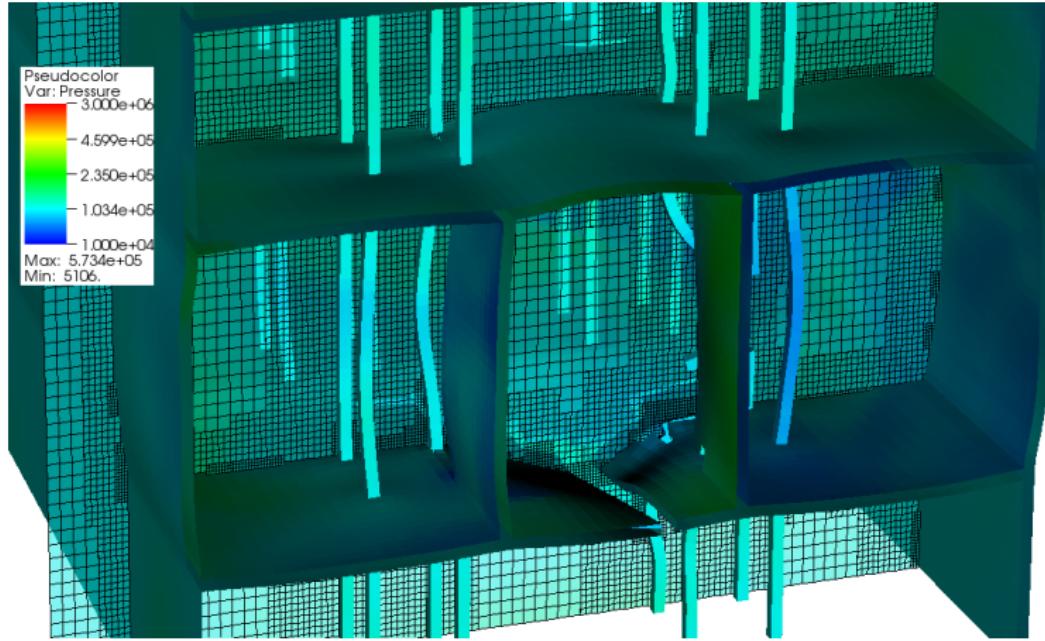
Blast explosion in a multistory building – II



Blast explosion in a multistory building – II

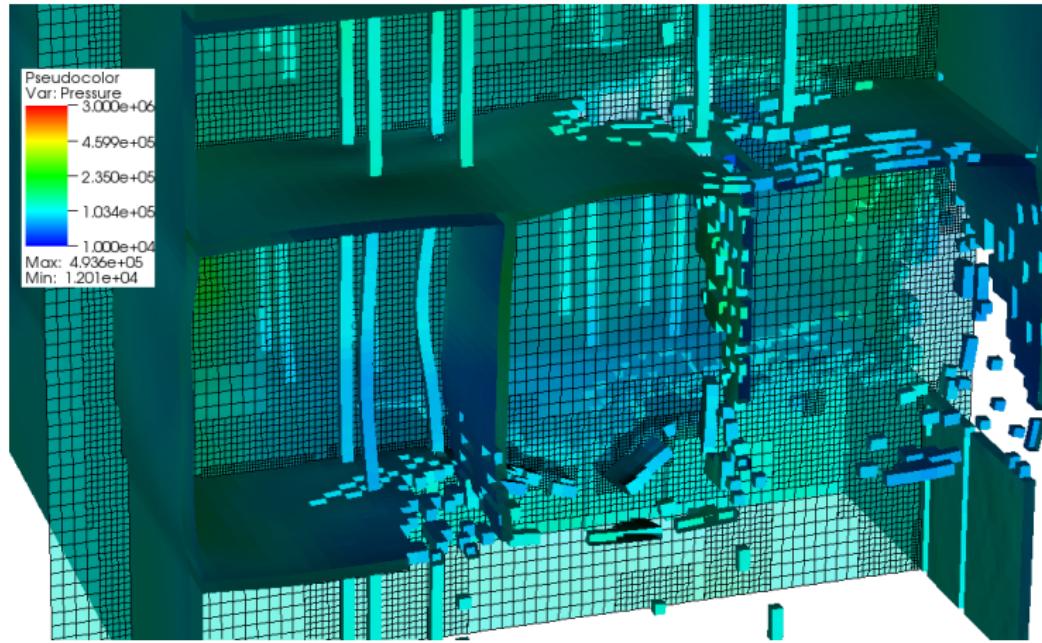


Blast explosion in a multistory building – II



Real-world example

Blast explosion in a multistory building – II



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